Installation, Operation and maintenance Guide

CPS_CPS 10 System



Part Number: NPCPSGB Revision: J.1



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- * The CPS model is not intended to be used as Life Safety Equipment

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2 years guarantee in normal conditions of use on parts and technical labour, return in our workshops, excluding consumables (sensors, filters, etc.)

General Information

Please read the following notice carefully before installation and start-up, paying particular attention to the end-user material safety instructions. This user's guide should be distributed to every individual involved in the installation, operation, maintenance or repair of the CPS system.

The information contained in this manual, the data and technical drawings are correct as of the date of publication. Should questions arise, please contact OLDHAM for additional information.

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This icon indicates that there is additional useful information for a particular topic.

Safety Warnings

Pictogram labels have been placed on the central controller to call attention to general use safety precautions. These labels are an integral component of the central controller. Replace any label that has peeled off or become illegible. The meanings of these labels are explained below.



Ground terminal



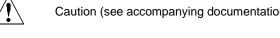
Safety ground terminal



Risk of electric shock



Caution (see accompanying documentation)





WARNING

The installation of this product and all electrical connections should be performed by a qualified professional, in accordance with the manufacturer's specifications and with the standards of authorities in the field.

Failure to observe these warnings may result in serious injury. Exercise great caution, particularly when working with electricity during installation (couplings, network connections).



European Union (and EEA) only. This icon indicates that in accordance with Directive DEEE (2002/96/CE) and with the regulations specific to your country, this product may not be disposed of with household waste.

Dispose of this product at a collection site intended for electrical waste, for example an official EEE (electrical and electronic equipment) collection site with a recycling or take-back program for authorized products which are available to consumers whose purchases are intended to replace old EEE products with new equivalents.

Failure to comply with regulations for the disposal of this type of waste can be harmful to the environment and to public health, as EEE products typically contain substances that may be dangerous. Your complete cooperation with the disposal of this product will help to ensure a more efficient use of natural resources.

Important Information

The modification of any piece of equipment or the use of any third party parts will automatically void all guarantees.

The central controller is intended to be used for precise applications of a technical nature. Exceeding the indicated values is strictly prohibited.

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Chapter 1

Overview of the CPS System

The system consists of:

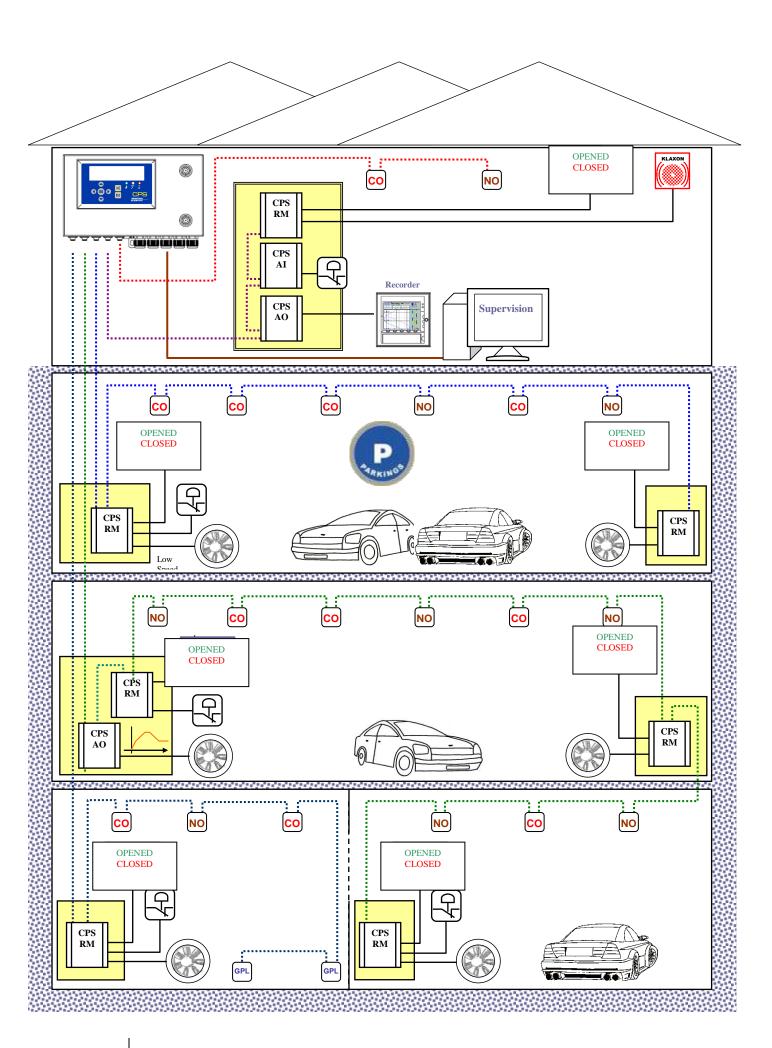
- a central controller for collecting readings and managing alarms;
- various addressable digital modules (sensor modules, relay modules, analog output modules, logic input modules);
- instruments and accessories to process alarms and actions

The CPS system can manage the detection of **10 different gases**, and all detectors are clearly localized and identified.

Data from each sensor is collected in the central controller in less than one second. If gas levels exceed the programmed limits, an audiovisual alarm is triggered and can activate the ventilation system in the affected area of the parking facility.

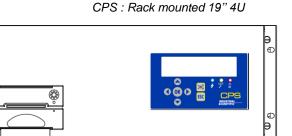
Use the COM_CPS software to program the central controller.

The system status can be quickly verified with semi-automatic calibration for various sensors.



The CPS central controller

CPS: Wall mounted version



The central controller is available in a 19" 4U (rack-mount) version or in a wall-mount version. It is designed to control:

- 256 digital modules distributed over 8 lines, with a maximum of 32 modules per line;
- 256 addressable relays max. distributed across all relay modules;

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- 224 logic inputs max. distributed across all logic input modules and relay modules.
- 256 analog outputs max. distributed across 4 analog outputs modules.

Modules are connected through a digital RS-485 network using JBUS/MODBUS protocol.

The central controller connects to 256 toxic sensors, and runs on only 24 Watts.

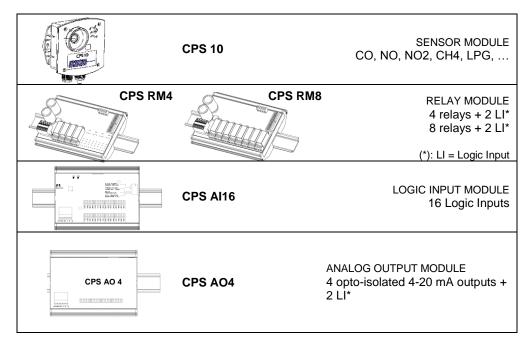
The central controller can be connected to a supervision system via an RS-485 output interface using ModBus protocol.

Optional features include:

- a battery back-up, ensuring continual operation in case of a power outage (approx. 1 hour for 50 TOX-type sensors);
- an integrated printer (rack-mounted version only) for recording alarms and events;
- an external printer (for both rack- and wall-mounted versions).

Digital addressable modules

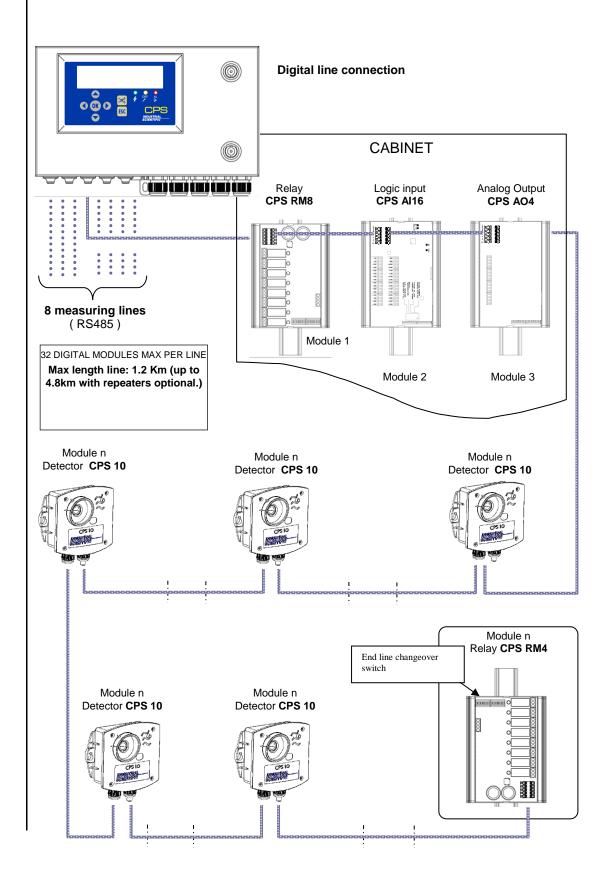
Various digital addressable modules can be positioned on the same line.



Digital linking

Modules are linked in-line via an MPI 22 or equivalent RS-485 double twisted pair cable, at least 0.22 mm² in diameter. One pair supplies power to the module, the second pair is used for the digital RS-485 link.

ISC – personnel should verify that the correct cable has been used in terms of type and capacity.



The COM_CPS software application

The **COM_CPS** software application is designed to help configure the CPS central measuring controller on a PC. COM_CPS software operations are addressed in a separate manual.

System and Hardware Requirements:

COM_CPS must be installed on a PC running Windows 2000 or Windows XP.

The minimum requirements to install COM_CPS are:

- Windows 98 SE, Windows NT, Windows 2000, Windows XP with 256 MB RAM, Windows VISTA.
- A CD-ROM drive
- At least 10 MB of free hard drive space
- A USB connection (cable not included) or a free RS-232 port (specific cable provided) to link the CPS central measuring controller to the PC.

Refer to the COM_CPS software instructions before installing or using the software, and before programming the central controller.

The COM_CPS software allows you to:

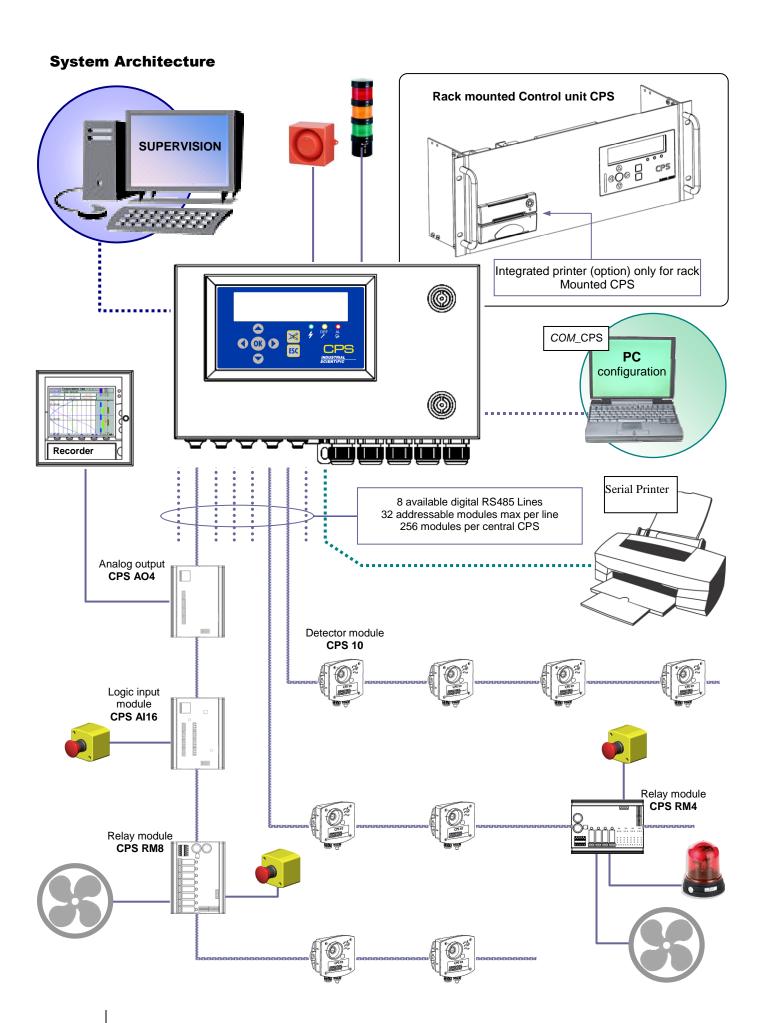
- configure one or more central controller(s) via PC;
- save settings and upload them later to the CPS central controller(s).
- view or modify central controller configuration data within the application.

The COM CPS software can be used to modify the following main configuration settings:

- STEL and TWA calculations
- Predefined status tables printing times
- Conditions that would activate an internal buzzer
- Communication speed for the RS-485 series connection with a master device
- Settings for various sensors and alarm values
- Personalized sensor add-on options
- Delay settings
- Rising edge or falling edge triggers
- Average alarm integration time
- Verification of explosive gasses
- Creation of installation architecture: sensors/relays

COM CPS

Whenever this sign appears in front of a chapter, the functions described in that chapter are configured with the *COM_CPS* software.



Chapter 2

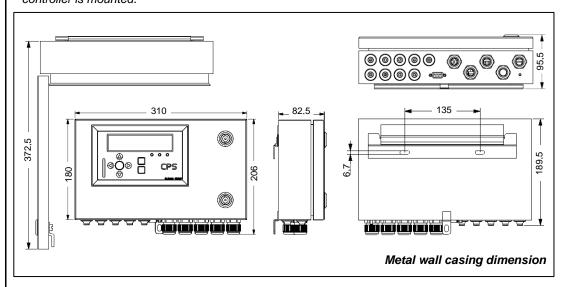
Assembly / Installation

Installation of the CPS central controller

The CPS central controller should be installed in a dry, climate-controlled area protected from explosive gases and dust. Ideally, the station should be located in a secure, accessible location under surveillance (security office, control room, equipment room ...).

Mounting the metal wall casing

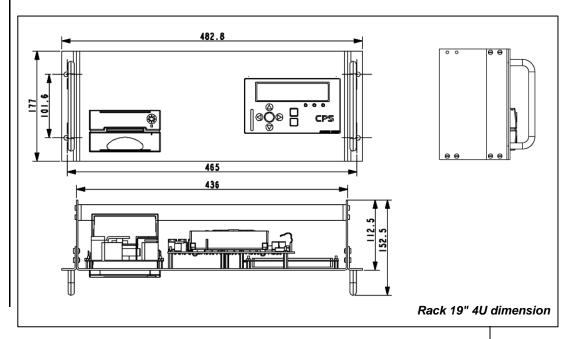
For the wall-mounted CPS in a metal case: The central controller cover opens at a 90° angle to the left. Make sure to leave adequate space to completely open the cover once the central controller is mounted.



Mounting the 19" 4U rack

The 19" 4U rack version CPS can be integrated into a rack or a 19" cabinet:

Mount the display at eye level for optimal viewing. Leave at least $\frac{1}{2}$ U (22 mm) on all sides of the central controller to ensure proper ventilation.



Installing digital modules

Mounting the CPS 10 sensor module

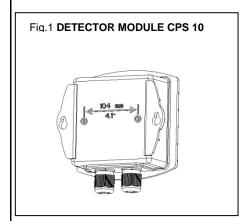
Mount the sensor modules on a flat surface using two screws (Fig. 1).

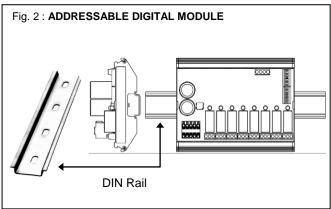
The modules should be placed in an accessible area, so that maintenance and inspection operations can be conducted as easily and as safely as possible. Nothing in the area should prevent the sensors from obtaining measurements of the ambient environment.

When mounting the sensor module on a vertical surface, position the cable glands on the underside of the module to ensure proper calibration.

Mounting the other modules

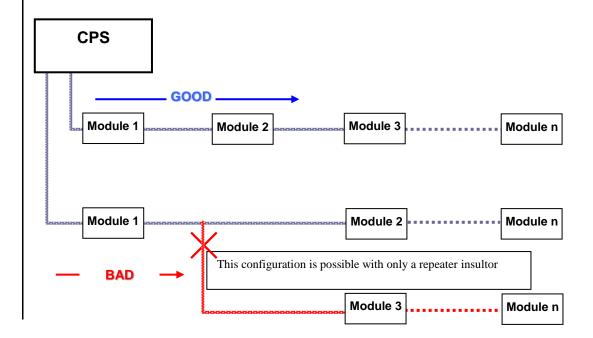
The other modules (relay, logic input, analog output) should be mounted on a DIN rail inside of a cabinet or an electric box. (Fig. 2).





Connection of modules in a line

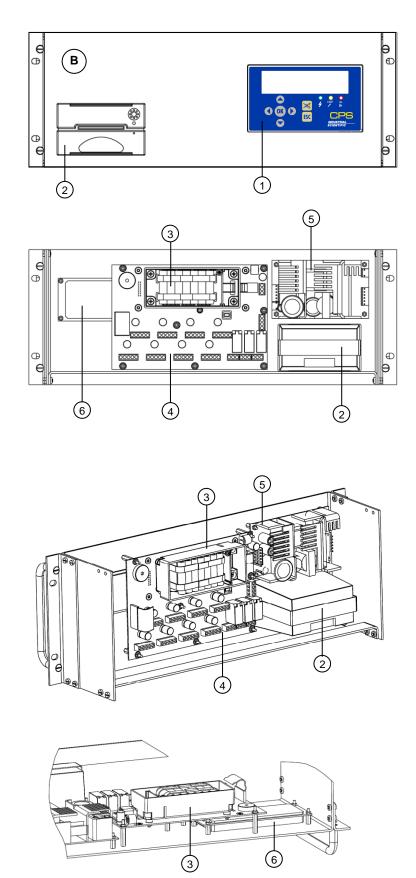
1 IMPORTANT: All modules in a line should be wired in-line from the central controller, not in a hub and spoke model.

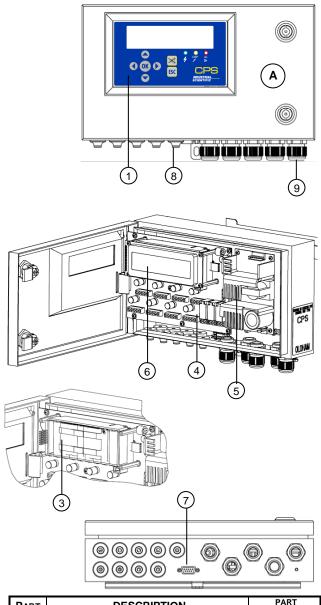


Chapter 3 The CPS Central Measuring Controller

View of rack-mounted CPS

View of wall-mounted CPS





PART	DESCRIPTION	PART NUMBER
Α	CPS WALL CASING	6 514 868
В	CPS RACK 19" 4U	6 514 869
1	CPS FRONT PANEL	6 122 477
2	AP1200 PRINTER	6 114 632
3	BATTERY PACK (OPTIONAL)	6 311 098
4	CPS MOTHERBOARD	6 451 596
5	24V 60W POWER SUPPLY BOARD	6 111 308
6	CPS CENTRAL CONTROLLER DISPLAY	6 133 707
7	RS232 SUB D9 CONNECTOR	6 116 263
8	M16 GROMMET: D5 to D7mm	6 131 166
9	M20 CABLE GLANDS : D6 to D12 mm M20 PE PLASTIC SCREW	6 143 504 6 143 529

Central controller electrical connections

Electrical connections are wired through the central controller MOTHERBOARD and the power supply 24V. For the CPS central controller (wall-mounted version), you must open the casing door to access the electrical panel.

Electrical connections must be done by a qualified professional. Observe all current Directives, notably the European Low Voltage Directive. Customers in France must observe standard NF C 15-100.



WARNING

Contact with voltage may result in serious injury or death.

Install all equipment and complete all wiring work before turning on the power.



WARNING

Improper installation can result in incorrect gas level readings or system failure.

Carefully follow all instructions to ensure proper system operation.

Main power supply

Test the current and voltage running through a network before making any connections. Never connect the device without first disconnecting the power supply. The central controller does not have an on/off switch.

Protect the central controller from upstream current with a 4A bipolar differential circuit breaker with a type D response curve. This circuit breaker must be included in the electrical installation of the building and must be placed near of the device and must be available for the operator. On the circuit breaker will be indicated that it is the circuit breaker of the device.

Main power supply 100-240VCA: connector terminals L, N, and PE of the power supply 24V (Fig 3) for wall-mounted version or see connector picture 4 for rack version..

Pre-cabled wires are used to connect to the 24 VDC power supply module. The transformer output connector is also hardwired to link to the 24 VDC central controller connector and to the (optional) integrated printer for the rack-mounted version.

Grounding the central controller

The central controller is intended for use in areas that meet the Class II requirements for overvoltage and degree of pollution as per EN IEC 60947-1. In order to comply with the standard, the internal ground terminal *must* be grounded (Fig 3).

Digital lines

The various digital modules are connected with "Bus" connectors (Fig. 5). Recommended cable: RS-485: 2 shielded twisted pairs, 100Ω .

One pair is used to power the module, and the other is used for communication. The cable shield or tress should be connected to the terminal: ____

 $oldsymbol{\dot{I}}$ Data wires and the schield wires should be cut as short as possible.

Internal relay dry contacts

The RCT dry contacts for the 3 internal relays R1, R2, and R3 are available on the CPS central controller motherboard on connectors J23, J24, and J25 (Fig. 7). Working load: 2 A at 250 VAC, 24 VCC.

Associated alarm type: R1 (alarm/fault), R2 (alarm), R3 (alarm).

RS-485 serial link out

Recommended cable:

RS-485 cable: 1 shielded twisted pair, 100 Ω . (Fig. 6).

MOTHERBOARD FOR RACK-VERSION CPS Fig. 3: POWER SUPPLY 24 VDC 0V +24 VDC 00 88 24 VCC Face avant Fig. 4: power supply 110-8888 R2 R3 240VCA Bus 3 Bus 5 Bus 1 Bus 7 **(1)** 000000000 Bus 8 Bus 4 Bus 6 Bus 2 N ①+Def ② Fig. 6: DIGITAL LIAISON RS485 Fig. 5: BUS 1 to 8 SUPERVISION SYSTEM DIGITAL MODULE LIAISON CPS 10 - CPSRM4/8 - CPSAI16 - CPSAO4 110-240VCA В +24Vcc Disjoncteur Cable RS485: 1shielded twisedt cable, Copper Blindages connection shield Bus RS485, Recommended cable: 2 shielded twisted pair cable, 100 $\boldsymbol{\Omega}$ [1 pair for module power supply, 1 pair for RS485 communication] Fig. 7: RCT contacts 0 J23 J25 J24 AL1 + DEF AL2 AL3 Minimum charge for RCT contact (resistive load) : 2A / 250 VCA - 30 VCC

Overview of the Motherboard

Part Connector function

(1)	110-240VCA main power supply (rack version)
(2)	24 VDC external power supply connection
(3)	110-240VCA power supply for (wall-mount) power supply module
(4)	24 VDC power supply output for power supply module motherboard + integrated printer (rackversion option) power
(5)	Internal contact relay outputs (RTC)

dry contacts, potential free

Part	Connector function
(6)	Digital addressable modules 8 line connectors for connecting digital modules (CPS 10 – CPSRM – CPSDI16 – CPSAO4)
(7)	RS-485 digital output links to a supervision system
(8)	USB serial interface (PC/COM_CPS connection for configuration)
(9)	RS-232 serial interface link PC/COM_CPS connection for configuration, External serial printer connection

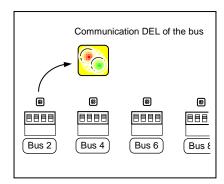
R1, R2, R3: central station shared internal relays

d Ф 0 **Power supply** board Φ \oplus e Motherboard Strap activation Wall mounted CPS buzzer Memory Lithium battery Buzzer Power supply (option) Oν +Vcc (2) Display board (9)(8) (7)Configuration switch (1) Communication DEL → ⊕ 8888 8888 8888 8888 R2 Bus 1 Bus 3 Bus 5 Bus 7 R3 8888 8888 8888 0 •• Bus 2 Bus 4 Bus 6 Bus 8 ΡĒ ① +Def ② (5) L N (6) 110-240VCA The wall-mounted version connects directly to the power supply board.

Inspecting the digital buses

Bicolor (red/green) LEDs located above each line start, on the motherboard, allows for inspection of the bus links as follows:

LED appearance	Status
Red + Green LEDs lit (LEDs blink rapidly, almost imperceptibly) Orange in appearance	Normal operation. Red LED→ question Green LED ← response
Red LED blinks once per second (green LED is off) Red in appearance	Communication fault. Missing or faulting module.
Irregular blinking	Poor communication quality
Both LEDs off.	No active modules

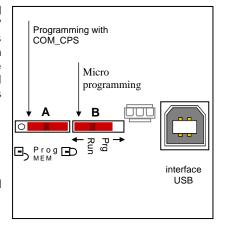


Mini-switches

Mini switch A allows the CPS controller to download and read the user program. When the switch is in the "MEM" position (open padlock), the user program memory is accessible and the message "switch open" is displayed on screen. The CPS central controller waits to download the program from the *COM_CPS* software. The CPS central controller goes into "shut-down" mode when mini switch A is in the "MEM" position.

When the COM_CPS software programming is complete, the mini switch should be flipped back to the "Prog" position (closed padlock), and the central controller should be rebooted to initialize all of the newly loaded settings.

Mini switch B only used for the central controller's internal microprocessor. It should always be in the "Run" position.



COM_CPS Internal relay and buzzer

The CPS central controller is equipped with 3 internal **relays** [R1, R2, R3] and a shared **Buzzer**. The operating settings for the relays and the buzzer can be set with the *COM_CPS* software (see table below).

The internal buzzer is activated when a specific program-defined event occurs (fault or alarm). All lines share relays R1, R2, and R3.

The buzzer's pitch will vary according to the alarm threshold. Alarms 1 and 2 have the same frequency. Alarms 3 and 4 have a different pitch, allowing the operator to distinguish between alarm levels.

The buzzer can be disconnected by removing the "buzzer activation strap" (J10) located on the motherboard next to the buzzer (cf -: Overview of the Motherboard).

Function / Component	Relay R1	Relay R2	Relay R3	Buzzer
AL 1	Х	Х	Х	X
AL 2	Х	Х	Х	X
AL 3	Х	Х	Х	Х
AL 4	X	Х	Х	Х
Module error		Х	Х	Х
System fault*		Х	Х	Х
Out of Range and Fault	Х	Х	Х	Х
Positive security		Х	Х	

- *: (System fault) alarm is triggered if there is a communication fault betweenmodules, a short-circuit in a power supply line, or a module inversion.
- X: Function can be activated or deactivated
- ■: Default configuration setting, cannot be changed by user.

USB / RS-232 serial connectors

The CPS central controller is equipped with a serial port which are used to:

- download the user software (see COM_CPS instructions);
- program the integrated micro application according to the position of mini switches on the board (factory setting).

I The serial port has 2 interfaces: USB and RS-232. Only one can be used at a time

The settings for the central controller can be modified after the program has been created. (Use either the USB or RS-232 adapter to connect the PC to the CPS central controller.

(See Chapter 7 - Program transfer).

USB Interface (1)

Use a USB cable to connect the PC to the CPS central controller running the COM_CPS application.

The USB interface emulates a serial port and is preferable to an RS-232 serial connection.

The corresponding USB driver must be installed before the PC is connected to the central measuring station (see *COM_CPS* instructions).

SUB-D 9 RS-232 Interface (2)

Use a cross-over RS-232 serial cable to load the user software.

RS-232 cable series reference number: **6 116 026**

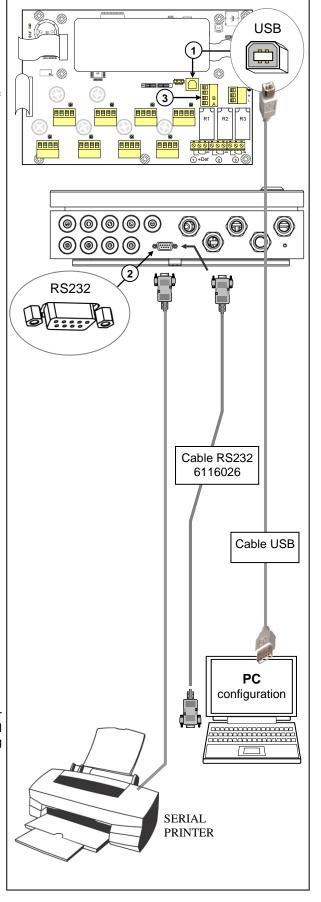
A serial printer can be permanently connected.

This would allow you to load the software via the USB interface without disconnecting the printer.

RS-485 serial connection (3)

The RS-485 serial port (3) is reserved for the supervision system and is composed of an RS-485 interface using JBUS/MODBUS protocol.

A table containing all of the important information pertaining to the central controller can be found in the corresponding annex of Chapter 8.



Printer (Optional feature)

Connection: Central controller RS-232 interface via an RS-232 serial cable.

Communication settings: 19200 Bd, 8 bit, no parity.

Event printing "on the fly."

Status table printing (choice of four printing schedules). For example: average readings over 20 minutes, 1 hour, or 8 hours, summary of alarm and relay statuses.

"Out of paper" functionality: no data is lost when the printer runs out of paper. Once more paper has been loaded, printing will resume where it left off.

Data flow is managed as follows: XON/XOFF Protocol

The printer is ON

The central controller sends data to the printer on start-up. If the printer's power supply fails or if the RS-232 cable is disconnected, data sent from the central controller will be lost.

In the event that the RS-232 cable becomes disconnected, it may be necessary to turn the printer off and on again to reinitiate data transfer.

The printer is OFF

No data is delivered to the printer. The central controller stops sending data when the printer signals the CPS central controller that it is no longer available (Buffer is full, out of paper, or printing stopped with the ON/OFF button).

The central controller will reinitiate data transfer once the printer signals that it is available (empty buffer, or signal through the printer's ON/OFF button or online button).

The front panel circuit

The central controller front panel circuit is equipped with:

1 LCD display: backlit, 2 lines by 32 characters and a pictogram line for viewing sensor readings and the zone in question, various test point data, settings, events, etc.



3 lights on the front panel of the central controller (green for power, yellow for errors, and red for exceeding thresholds) serve as constant system status indicators.

7 keys to select on-screen information and/or validate certain operations via menus. The menus are available in English, French, German, Spanish and Dutch.

Display Screen



No alarms or errors



Icon associated with one or more alarm icons indicates (by blinking) that the associated alarm is an averaged alarm.



SOLID = instantaneous alarm 1 BLINKING = averaged alarm 1 (takes priority over solid state)



SOLID = instantaneous alarm 2 BLINKING = averaged alarm 2 (takes priority over solid state)



SOLID = instantaneous alarm 3 BLINKING = averaged alarm 3 (takes priority over solid state)



SOLID = instantaneous alarm 4 BLINKING = averaged alarm 4 (takes priority over solid state)



SOLID = stable signal in hysteresis interval (calculated over 1 minute)



SOLID = signal increased in relation to the minute before BLINKING = Exceeding the scale (takes priority over solid state)



SOLID = signal decreased in relation to the minute before BLINKING = Negative fault (takes priority over solid state)



SOLID = buzzer on



SOLID = calibration underway



SOLID = LS (low speed) relay control active



SOLID = HS (high speed) relay control



SOLID = Error



SOLID = mains power supply OK BLINKING = battery or mains power supply problem

Keys





Keys primarily used to modify values (ex: line number)



Keys primarily used to navigate menus or to change variable current (ex: go from line number to sensor number)



Key used to validate a menu or an input that would alter system operation. (ex: activation of a relay)



Key used to return to a previous menu screen or to cancel a selected value before it has been validated.



Key used to acknowledge a locked alarm (programmed for manual acknowledgement) or to dismiss a buzzer relay after its holding time, even if an alarm is still active.

Lights



Green LED: power supply status indicator SOLID = OK

BLINKING = power supply problem (no power to main or problem with the battery pack)

Orange LED: indicates the presence of one or more

Red LED: signals the presence of one or more alarms.

Alarm thresholds

Six alarm thresholds can be programmed and adjusted for each sensor:

Alarm 1, Alarm 2, Alarm 3, Alarm 4, Out of Range and Fault.

Alarms 1 - 4 can be:

- Instantaneous;
- delayed (0 to 3,600 seconds);
- averaged (period of 1 to 480 minutes).

This makes it possible to calculate STEL and TWA values.

So, for example, you could choose to activate Alarm 1 if the average calculated levels over a period of 8 consecutive hours exceeded 50 ppm, and Alarm 2 if average levels over a period of 10 minutes exceeded 100 ppm, and Alarm 3 if the instantaneous reading exceeded 200 ppm.

Averaged alarms are only triggered at the end of a complete time interval.

If the line or the detector module stops, average value calculations are halted and will only begin again once the line or the detector module has been reactivated.

Both the instantaneous and averaged alarms can be set to trigger on an increasing value (rising edge) or on a decreasing value (falling edge).

- **Rising edge**: alarm is activated when levels increase. Use this option for sensors measuring Explo, CO, H₂S, etc.
- Falling edge: alarm is activated when levels decrease. Use this option for O₂ sensors, for example.

Out of Range alarm: can activate an alarm, a relay, or an LED.

"Verification" option: this option is activated for explosive gases. When a "verification" alarm occurs, the level displayed will be frozen at the maximum value until it is acknowledged (manually or automatically) and on the condition that the gas levels have fallen under the alarm threshold.

Example of ventilator command functionality for CO/NO detection

Alarm threshold	CO (ppm)	NO (ppm)	RESPONSE	
Alarm 1	50	25	Ventilators start on low speed	
Alarm 2	100	50	Ventilators go to high speed	
Alarm 3	150	75	Max speed ventilation + alarm lights in the surveillance area	
Alarm 4	200	100	Visual & audible alarms + restricted area access + evacuation orders for individuals in the area	

Alarm acknowledgement

Alarms can be rearmed in two ways:



Manual acknowledgement: the audible alarm can only be dismissed after the "Acknowledge" button on the CPS central measuring controller has been pushed; or

Automatic acknowledgement: the audible alarm will be automatically dismissed once the alarm condition has ended.

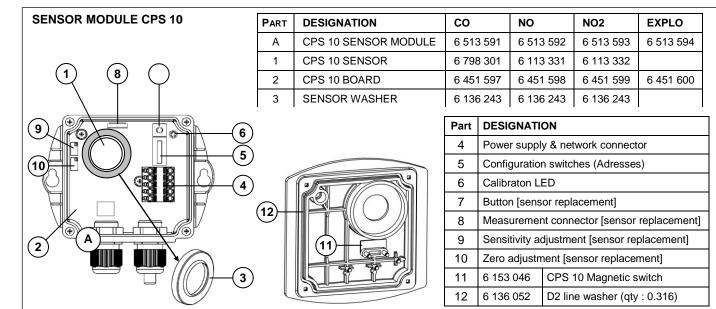
If an alarm is triggered, a corresponding message will appear on the screen, an audible alarm (BUZZER) is activated, and the red LED on the front panel is illuminated.

Touching the "Acknowledge" button once will remove the message from the screen and will turn off the BUZZER.

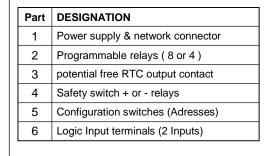
Touching the "Acknowledge" button a second time will re-arm the programmed alarms. These alarms will not turn off until the concentration of gas falls below the threshold.

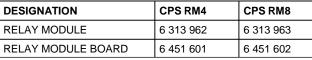
Chapter 4 Digital Modules

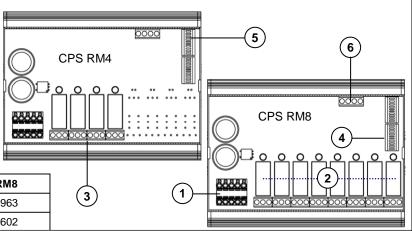
View of Digital Modules



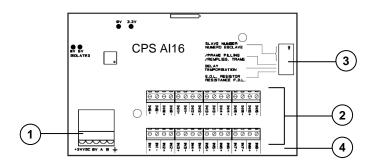
RELAY MODULES CPSRM4-CPSRM8





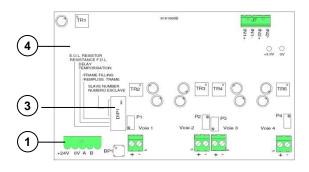


LOGIC INPUT MODULE CPS AI16



Part	DESIGNATION		
1 Power supply & network connector			
2 Logic input terminal (16 Inputs)			
3 Configuration switches (Adresses)			
4	Module board		

ANALOG OUTPUT MODULE CPS A04



DESIGNATION	TION CPS AI16	
MODULE	6 313 964	6 313 980
MODULE BOARD	6 451 603	6 451 614

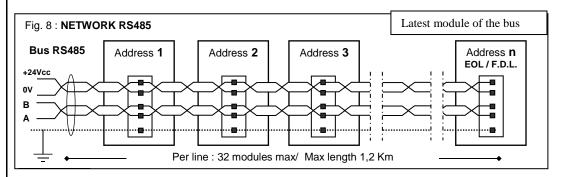
Connecting Digital Modules

General topology of the RS-485 network

Modules are connected in "parallel" in the RS-485 network, comprised of a 1 twisted pair cable for signals, 1 or more pairs to supply power to the modules, and 1 shield wire.

A 120 Ω end of line resistor (**EOL RESISTOR**) should be placed at the last module in the line, at the end of the bus (see Chapter 6 - End of Line Resistor).

The modules are equipped with a double connector, which can be split to easily connect conductors and also allows you to isolate the module while maintaining line continuity.



Wiring the digital network

The sensor module has two cable glands. One connects to the input wire, and the other connects to the output wire which is routed to the next module.

The modules should be wired with RS-485 shielded twisted pair cable, with a normal impedance of 100 Ω , of at least 0.22mm² in diameter. +24VDC, 0V A and B terminals are linked to +24VDC, OV terminals A and B in other modules in the line, and then linked to the connector corresponding to the central controller. The cable shield should be connected to a ground terminal marked with the following symbol: (Fig.9).

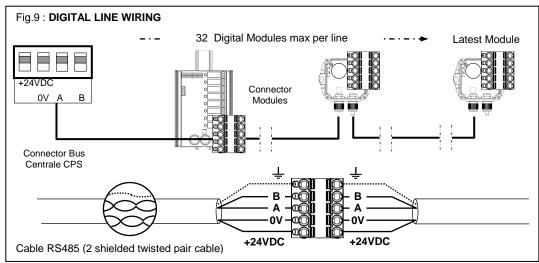


An improper installation can cause incorrect gas level readings or system failure.

Do not run cable near equipment such as motors, transformers, or any lines generating a large magnetic field.

Always check to ensure that the cables are completely separated from other circuits.

1 Do not leave any stripped wire ends exposed. To guard against electromagnetic disturbances, the data cables and the screen (tress) cables should be cut as short as possible



Configuring the communication settings

Slave address

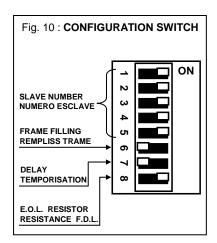
All modules in a line should be identified with a unique slave number. Switches 1-5 on the **configuration Switches** unit (Fig. 10) contained in each module, allow you to set a binary numerical address (1...32).

Possible combinations are listed in the address table below.

Notes: The physical address of a module (1...32) should be identical to the address recorded in the central controller configuration program with *COM_CPS*.

When replacing a module, set the configuration switches in the new module to the same position as those of the module being replaced.

1 Switches 6 (FRAME FILLING) and 7 (DELAY) should be in the OFF position (unused options).



End of line resistor

The last module in each line should be equipped with an end of line resistor.).

1 This switch should be in the OFF position for all other modules in the line.

Address Table

SS	SWITCHES					
Slave Address	ON = 1; OFF = 0					
S Ac	1	2	3	4	5	
1	1	0	0	0	0	
2	0	1	0	0	0	
3	1	1	0	0	0	
4	0	0	1	0	0	
5	1	0	1	0	0	
6	0	1	1	0	0	
7	1	1	1	0	0	
8	0	0	0	1	0	
9	1	0	0	1	0	
10	0	1	0	1	0	
11	1	1	0	1	0	
12	0	0	1	1	0	
13	1	0	1	1	0	
14	0	1	1	1	0	
15	1	1	1	1	0	
16	0	0	0	0	1	

SS	SWITCHES							
Slave ADdress	ON = 1; OFF = 0							
AE	1	2	3	4	5			
17	1	0	0	0	1			
18	0	1	0	0	1			
19	1	1	0	0	1			
20	0	0	1	0	1			
21	1	0	1	0	1			
22	0	1	1	0	1			
23	1	1	1	0	1			
24	0	0	0	1	1			
25	1	0	0	1	1			
26	0	1	0	1	1			
27	1	1	0	1	1			
28	0	0	1	1	1			
29	1	0	1	1	1			
30	0	1	1	1	1			
31	1	1	1	1	1			
32	0	0	0	0	0			

CPS 10 Detector Module

The CPS central controller accepts 10 types (or 10 different configurations) of sensors. The type of sensor used in the module depends on the gas being monitored. Electrochemical sensors are used to measure CO, NO, NO₂, for example, while catalytic sensors measure gases such as GPL, CH₄, and H₂).

Available Detector Types

Sensor		Measurement			Sensor life expectancy	
Carbon monoxide	CO	: (0 300	ppm	36 months	
Nitric oxide	NO	: 0	0 100	ppm	24 months	
Nitrogen dioxide	NO_2	: 0	30.0	ppm	24 months	
Methane	CH₄	: 0	0 100	% LEL	48 months	
Liquefied petroleum	LPG	: 0	0 100	% LEL	48 months	
Hydrogen	H_2	: (0 100	% LEL	48 months	

Sensor module fault

In the event of a sensor module fault, gas levels are no longer taken into account, and all alarms are cancelled, except for the negative threshold (or fault) which is activated. Average values are no longer taken into consideration and the calculation of average values is paused.

If a sensor faults, it can be replaced while the central controller is still running (hot swap) without replacing the detector.

Detector settings

The following settings apply to each type of detector:

- The abbreviated name to be displayed on the central controller: NO, CO, CO₂...
- The name of the gas: Carbon monoxide, Nitric oxide, Oxygen, Methane ...
- **Unit:** ppm, LEL, %v/v ...
- Range with display format: 100, 10.0, 1.00, ...
- Actionable thresholds:
 - o 4 instantaneous thresholds: 0-100% measuring range,
 - 4 averaged thresholds: 0-100% measuring range, (time interval programmable from 1 to 480 minutes).

If the operating time is inferior to the averaging time interval, the averaging time interval is ignored.

An instantaneous threshold is associated with an averaged threshold to generate an alarm. These two thresholds can be set to trigger on the rising edge (increasing alarm) or the falling edge (decreasing alarm).

Alarm delays (0s to 60 min):

Each of the 4 alarm thresholds can be delayed. If gas levels are in excess of an alarm threshold for an amount of time inferior to the programmed delay, the alarm will not activate.

The alarms can be acknowledged automatically once the alarm is turned off, or manually when the gas levels are once again under the threshold.

■ Fault thresholds:

- o "underscale" negative signal (exceeding the lower threshold): -10% of the range.
- o "SUP" out of range (exceeding the upper threshold): +120% of the range.
- o "Verification" for all explosive gas sensors, in case an LEL threshold is passed, the SUP alarm remains on even after levels fall under the threshold. The fault alarm is also triggered.

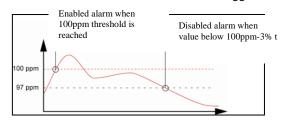
Hysteresis:

Max. 1% of range. Default value = 0%.

Example (see opposite page):

Measurement range = 300 ppm; Alarm = 100 ppm; Hysteresis (1% of range) = 3 ppm

Level at which alarm can be dismissed = 97



External relay module

The relay module is available in two versions: CPS RM4 (with 4 relays) and CPS RM8 (with 8 relays). It also has two logic inputs (LI) which can be activated.

In maximum configuration, the CPS can manage 256 relays (ex: 32 modules with 8 relays each). For more information about the logic inputs: see: Logic inputs module.

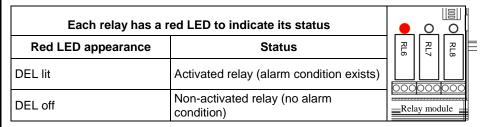
The relays are individually programmable. The operation of each relay depends on its configuration and its function.

Each of the 6 sensor alarms [AL1 - AL2 - AL3 - AL4 - Out of Range - Fault] can control one or more of the 256 relays. Several events can be linked to one relay.

In case of a module relay fault, all relays of this module are restarted.

The CPS central controller will change the relay status unless they belong to a different module type. Restarting will resolve the problem.

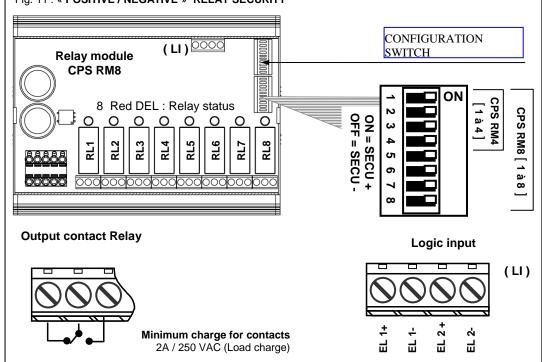
Relay status lights



"Positive/negative" relay security

In addition to switches of CONFIGURATION, RELAY MODULES INCLUD SWITHCHES OF POISITVE AND NEGATIVE SECURITY CONFIGURATION. Flip the switch to **ON (positive security)** or **OFF (negative security)** as desired. Each switch acts on its corresponding relay (switch 1 \rightarrow relay RL1, switch 2 \rightarrow relay RL2, etc.). (Fig. 11).

Note: Only switches 1-4 are active in the CPSRM4 module.
Fig. 11: « POSITIVE / NEGATIVE » RELAY SECURITY



COM_CPS

Relay configuration

"Normal" relays

The relay is activated when an alarm occurs and is deactivated when the alarm condition ends.

The variables acting on a relay in alarm status are:

- Alarm delay
- Automatic / Manual acknowledgement
- Forced state change via the CPS menu
- Forced state change via a logic input command

"Buzzer" relays

The "Buzzer" relay is used to control an audible alarm.

It can be re-armed with the [**Acknowledge**] key on the central controller, even if the alarm condition has not changed.

The occurrence of a new alarm will reactivate the relay and reset the delays.

The "Buzzer" relay can be automatically dismissed before the end of the alarm with a 15 to 900 second delay (standard setting for "Buzzer" relays) or manually, even if the alarm condition has not changed. It can be configured with a minimum operating time of 1 sec. to 5 min.

The variables acting on a relay after an alarm has occurred are:

- Alarm delay
- Automatic / Manual acknowledgement
- Forced state change via the CPS menu
- Forced state change via a logic input command

Alarm and/or "Buzzer" relay delays

Alarm d	lelays	Relay delays	
		"Buzzer modes"	
Instantaneous Alarms	Averaged Alarms	Min. activation time: 0 300 seconds	
1 3600 seconds	1 480 minutes	Acknowledgement time: 15 900 seconds	
Standard settings for	r each sensor type	Standard settings for all "Buzzer relays"	

"LS/HS" Relays

Low speed (LS) relays and high speed (HS) relays are always used together, allowing you to control a parking facility ventilation system at two speeds.

LS (low speed): The relays are designed to control slow ventilator speed (star-triangle configuration for a two-speed ventilator).

HS (high speed) : The relays are designed to control high speed ventilator speed (star-triangle configuration for a two-speed ventilator).

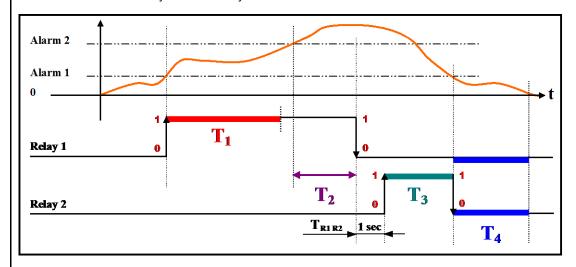
The working logic of the relays defined hereafter, takes into consideration the start-up and shut-down intervals during which very high levels of current may occur, capable of damaging motor windings if phases occur in the incorrect sequence.

"LS / HS" Operation

Requirements: Alarm level 1 < Alarm level 2

The LS relay is activated by Alarm 1

The HS relay is activated by Alarm 2



Phases		Action operation	Default Delay*
T ₁	Min. duration LS operation Adjustment(s): [1 32767]	Minimum duration, in seconds, during which the ventilator operates at low speed	5 min.
T ₂	HS operation delay Adjustment(s): [2 32767]	Minimum duration for Alarm 2, after which the ventilator switches to high speed	15 min.
T _{R1}	LS/HS transition time 1 second (cannot be changed)	Transition time between Relay 1 and Relay 2 is 1 second (standardized throughout the central controller)	1 sec.
T ₃	Min. duration HS operation Adjustment(s): [1 32767]	Minimum duration, in seconds, for the ventilator to operate at high speed. HS relay deactivated if Alarm 1 condition ends	10 min.
T ₄	LS-HS stop delay Adjustment(s): [1 32767]	Duration, in seconds, after low or high speed ventilator operation has been stopped, before the ventilator can be restarted at low speed.	10 min.

Time values T_1 , T_2 , T_3 and T_4 can be modified. When the "Sensor simulation" menu is used (see the chapter on the maintenance menu/simulation on page 43) the times are decreased, by default, to 12 seconds, 24 seconds, 36 seconds, and 24 seconds, respectively.

Note: An underscale alarm (= fault) activating a LS or HS relay will force the relay into HS position (with respect to the defined time).

"Forced ventilation" function

This is a forced relay state change via the CPS menu. This function allows you to block or release the HS (high speed) command at specified times.

Forced relay state change via a logic input command

In both cases the response is immediate and priority safety settings are maintained: HS takes precedence over LS, and both relays are shut-down if there are contradicting signals.

Logic Input Module

COM CPS

This module contains 16 logic inputs, linking priority commands, such as fire extinguishers directly to the central controller.

A maximum of 224 total logic inputs across all modules can be activated.

Example 1: 112 modules having 8 relays each, with activated inputs.

Example 2: 7 modules with 16 logic inputs with activated inputs.

Each input can override all other commands to activate or block up to 256 relays.

Priority inputs

Two levels of input priority can be managed on each module with the COM_CPS software.

Priority inputs have control of the other inputs (all of the non-priority inputs are "blocked" when a priority input is activated).

In the event that two different inputs of the same priority level send contradicting orders, the relay is shut-down.

In the event of a fault, the inputs are set to zero.

CPS Al16

CP

COM_CPS Analog Outputs Module

This module is comprised of 4 opto-isolated 4-20 mA analog outputs which can be individually activated or deactivated.

defined in the program

Activated: the output analog signal (4-20 mA) varies, according to the input

Deactivated: the analog output signal will be frozen at 0mA, regardless of the input signal.

Several events can be linked to one output. In this case, the largest analog value will be recopied onto the analog output.

The output module also has two logic inputs (LI), identical to those on the "Logic input" module.

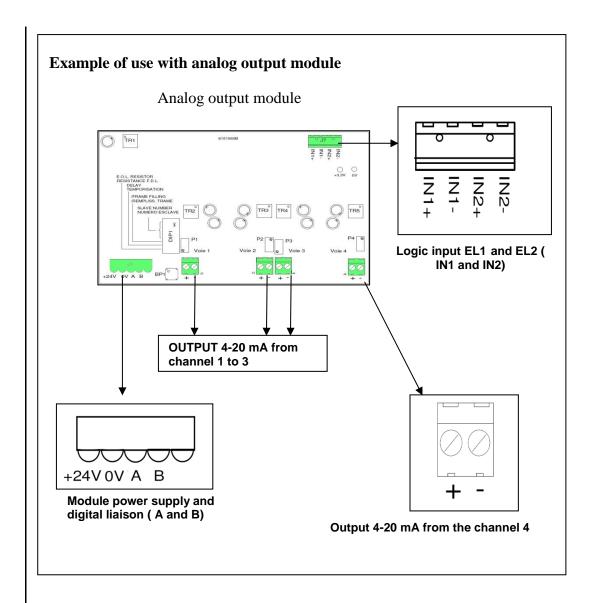
A "slave address" for the module can be set with the "DIP" switch (DIP1).

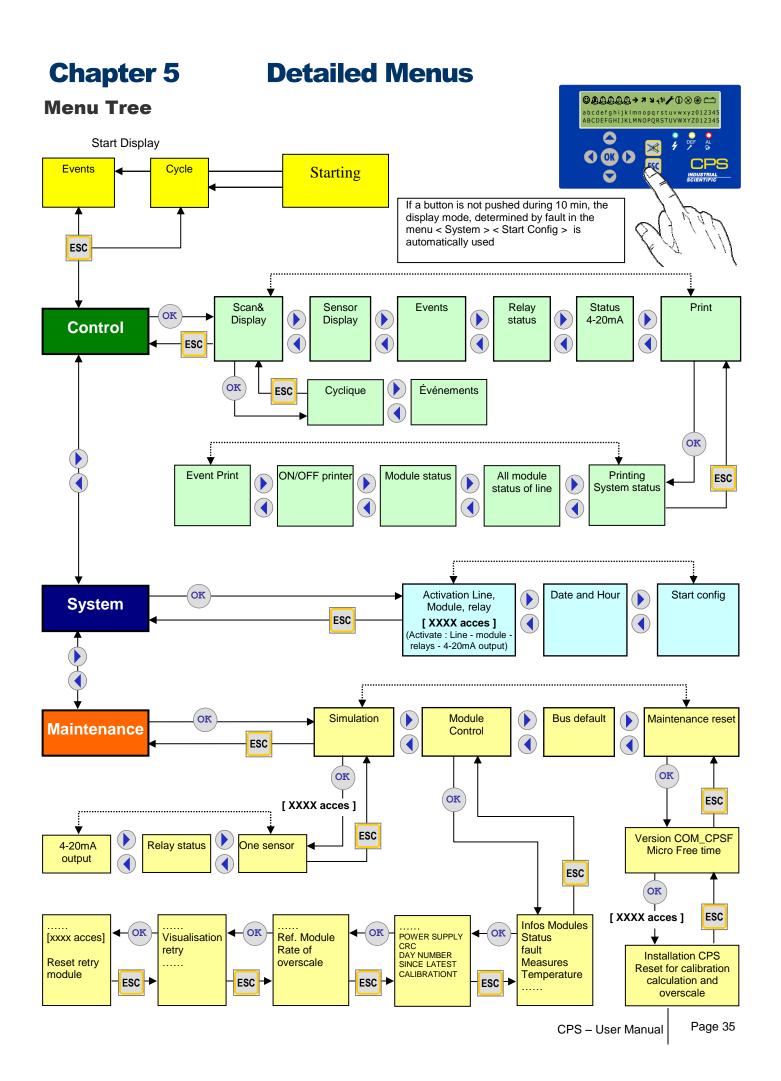
An analog output OFF command from the central controller corresponds to 4 mA.

An analog output ON command from the central controller corresponds to 20 mA.

Connections:

Analog output module





Start-up Phase

No faults or alarms are processed during the first minute after start-up. During this phase, the central controller runs a Checksum test (1), a RAM test (2), a line start-up (3) and a module mapping test with a program stored in its memory.

Voltage builds progressively in the lines. Progress bars show the overall progress for line power-up.

Only the power-up of activated lines is shown (identified by a diamond " \diamondsuit " during the initial power-up phase, and by a black square " \blacksquare " at the end.)

An exclamation point "!" indicates a short-circuit line fault. The line can be reactivated through the menu system.

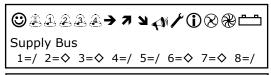
Next, a sensor stabilization phase occurs (4) during which time, the alarms are deactivated.

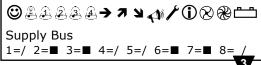
An inspection phase immediately follows in order to verify that the configuration program set with the *COM_CPS* software correctly maps to the modules installed and activated.

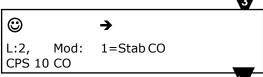
If no errors are found, the program runs normally. If errors are detected, the modules in question will be flagged as faulting.











After the start-up phase, the screen will display information pertaining to the selected mode: events (a) or cyclic (b). The central controller begins to process data coming in from the various modules.

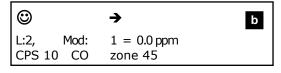
In cyclic display mode, when no alarms are triggered the levels from each sensor are displayed on the first line of the display screen.

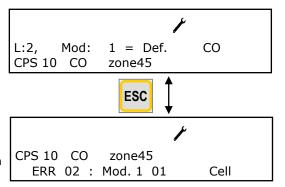
In case of a power outage, the program configuration will be saved. When the controller is turned on, the last program installed by COM_CPS will be loaded.

If a sensor faults, the message "Def" will replace the reading value. If the power supply is interrupted within a line, the two points in front of that line will blink. Identify the problem by touching the [ESC] key to display the error message.

If the gas level exceeds a high or low threshold, "Ovs" will appear on the display screen where the value for that sensor would normally appear. This message will display simultaneously with a blinking arrow (pointing up or down, depending on the situation).







Control Menu

Normal Display

Alarm pictograms will appear and disappear in along with the alarm conditions detected by a given sensor. The display shows gas level readings, which may not always be identical to the status of a relay. Under normal conditions, alarm pictograms reflect relay status.

Example: LS and HS relays are configured to run on a delayed trigger. Pictograms do not take this delay interval into consideration. So it is possible that the LS or HS relay is on, while the alarm pictogram does not display on screen, due to the alarm delay.

Cyclical display

This menu allows you to view all of the activated sensors on screen, at a display rate of one sensor every two seconds.

Event display

This menu allows you to view the status of all sensors in alarm mode, faulting, or in calibration, at a rate of one sensor every two seconds.

Sensor Display

This menu allows you to freeze the display on a specific sensor by selecting the line and the module number (The program automatically selects active sensor modules).

Touching the [**OK**] key once will bring up the sensor name, the abbreviated gas name, the gas level and unit of measure (ppm, % LEL, \$v/v).

If the sensor is faulting, "Def" will display in place of the level reading.

Select the line or the sensor (if appliable) using the [\P] [\P] (horizontal) keys.

Select the line number or the sensor number (if appliable) using the [$^{\blacktriangle}$] [\checkmark] (vertical) keys.

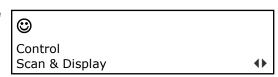
Press [OK] to select the sensor.

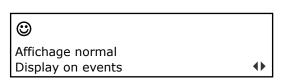
Press [OK] a second time to display both the gas reading level and the 4 averaged readings if average readings were activated. If averaging was not activated, < *** > will display on screen.

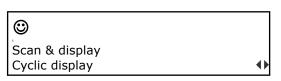
If a communication fault occurs, the value will be replaced by < *** > and the averages will stop on the last calculated value.

For all other faults, the gas level will be displayed in order to help the user identify the problem.

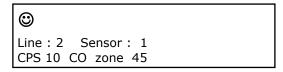


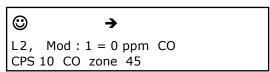




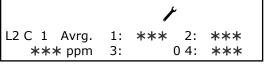












		7	
L2 C 1 Avrg.	1:	*** 2:	***
-37 ppm	3:		

Events

This menu can be used to search through a history of the most recent 1,200 events. A record of these events can be printed. State changes are recorded in the history.

If Alarm 1 ends and Alarm 2 is triggered, AL2 ON will be recorded.

Examples

- (a) The shut-down of a line causes the shut-down of alarms and relays for that line.
- (b) The "fault" alarm is triggered for module 3, line 1.

Other examples:

Module 2, line 8 turned on

30/06/06 (day/month/year) 14:40:36 L:8, Mod:02 Module ON

Alarm 2 triggered

30/06/06 14:49:37 L:8, Mod:02

Alarm 2, OFF \Rightarrow ON

State change for Relay 2 (command relay)

30/06/06 14:49:37 L:8, Mod:29

0

Line

Control

Events

Relay 2 Normal ON

<u>Conditions for Alarm 2 end</u>
30/06/06 14:51:03 L:8, Mod:02

Alarm 2, ON ⇒ OFF

Acknowledgement action

30/06/06 14:55:21_

ACKNOWL

State change for Relay 2 (relay shut-down)

30/06/06 14:55:21

()

(a)

Relay 2 Normal OFF

Relay Status

This menu displays the status of a relay in a given module. Increments for the preceding and following modules in the line are automatically calculated.

Display the status for the selected relay by pressing the [OK] button. This screen will show the module, its mode of operation (Normal, Buzzer, LS, HS,...) and its status (ON, OFF).

© Control

25/06/07 19:06:02

2 OFF



(3)

Relay status

Line: 2 MoDule 1 Relay Module Level-1

(a): (LS / HS) - Delays

(a): (Buzzer Relay) - Acknowledgement time

(b): (Buzzer Relay) - Min. activation

Relay N r 1: OFF (a) 0 2-1-1 Low S (b) 0

4-20 mA Output Status

This menu displays the outputs for the selected module. The value is displayed in mA.

Multiple inputs can be linked to one output. In this case, the largest analog value will be recopied onto the analog output.

Control
4 - 20 mA Status

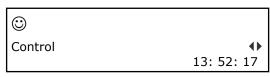
Activated analog output: the 4-20 mA output signal varies according to the input.

Deactivated analog output: the 4-20 mA output signal will be frozen at 0mA, regardless of the input signal. The output current for each channel will vary between 0 and 24.5 mA.

Printing

"System status" Report

This menu is used to initiate the printing of system status reports. The second part indicates the fault status for all of the modules in each line. Each hexadecimal number corresponds to a module, with Module 1 being on the left, and Module 32 on the right.



0 = OK

- 1 = Communication error
- 2 = Module recognition error
- 4 = Fault triggered by a module fault word.
- X = (no programmed module)



If the system detects an abnormality in either the name or the range of a gas, the letter N will blink on the screen

"Status for all line modules" Report

Sensor module: the printed reports will contain both the reading and the averages if averages are activated.

Relay module: the printed reports will contain the status of each relay and of each relay's logic inputs.

Logic inputs module: the printed reports will contain the status of all logic inputs.

"Module status" Report

Prints the status of every module in the selected line. See previous paragraph.

"Printer On/Off" Report

Use the [▲] and [▼] keys to activate or deactivate the printer.

When the printer is activated, the **COM_CPS** cannot be used to for reading or configuration. The configuration mini-switch (A) must be placed in the open padlock position to enable communication between the serial port and the **COM_CPS** software (cf "Programming mini-switches").

"Event" Report

This feature allows you to print all of the most recent events stored in memory (up to 1,200).

Calibration Report: The calibration data for a sensor is only printed at the end of the calibration process. The record will consist of a title, the line number and module number and 6 readings if a complete calibration has take place:

Calibration1Sensor $4\ 01\ CO$ X01 = 00004Zero value before starting procedureX02 = 00000Zero valueX03 = 00000Zero value after procedureXf1 = 00095Value of the concentration of calibration gasXf2 = 00100Value of the response to the gasXf3 = 00100Value of the reading at the end of the procedure

Acces code

An access code is required to access certain menus. The access code is made up of 4 hexadecimal numbers. If the wrong code is entered three consecutive times, the code will be deactivated until all menus have been exited or until after 10 minutes of inactivity. The *COM_CPS* software can be used to modify the access code.

The default access code is: 1 0 0 0

System Menu

Line, Module, Relay Action

Line activation

The selected line is displayed along with its number and name.

To go to a different line, use the

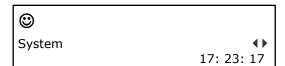
[♠] [▼]. Change the status by pressing the [**OK**] key, and then pressing the [◀] [▶] keys, followed by [**OK**].

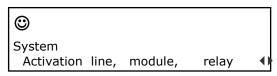
If the line is shut-down, the line number will flash intermittently with a cross sign. If the module does not correspond with the CPS central controller COM_CPS-created program, its status is reported as faulting.

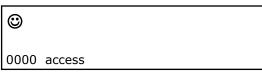
Notes: If the line is shut down by the COM_CPS software, it is impossible to turn it on.

A line is fully activated approximately 5 seconds after start-up.

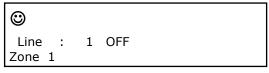
A thermal fuse protects the line's power supply from short-circuits. Should a short-circuit occur, a fault word will appear in the menu and an error message will be recorded in the event log. After the short-circuit, the line must be reactivated via the menu.

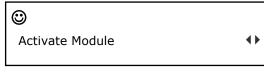


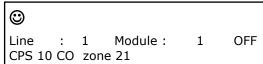












Relay activation

Use the same "Relay Status" menu to select a relay. After pressing [**OK**] to select the relay, you have three options:

< Normal > = Relay functions normally (triggered by alarms)

< ON > = Relay in forced operation (can only be shut-down by a logic input)
< ON > = Relay in forced shut-down (can only be turned on by a logic input)

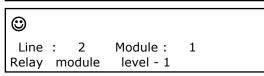
Special case: LS and HS relays

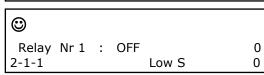
For safety reasons, deactivating a LS or HS relay via the CPS central controller shuts down of the two relays and restarts their timing devices.

If a logic input or a command from the CPS central controller activates a LS or HS relay, the relay will be activated. The relay's activation time is set to the maximum value. In other words, the forced relay shut down ends when logic inputs no longer command the relay or after the end of an alarm condition which could control the relay.

Similarly, if an alarm triggers a HS relay, a LS relay cannot be activated.







The forced activation of a HS relay takes priority over scheduled HS freezes.

Activating analog outputs

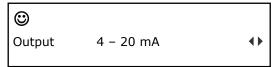
Choose the 4-20 mA output for the selected module. Pressing [OK] will force a start-up or shut-down for the 4-20 mA output.

- The shut-down freezes the output at 4 mA.
- The start-up freezes the output at 20 mA.

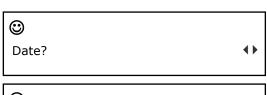
Date and Time

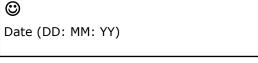
△ Changing the time settings will reinitialize LS and HS delays!

Example: If the HS relay is activated and the time is changed, the HS relay will stop so that the LS relay can operate according to the predetermined delays.











0 3/ 0 7/ 0 7

Start-up Configuration

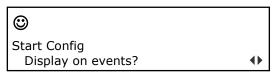
This menu is used to select which menu will display by default upon start-up and after 10 minutes of keyboard inactivity.

The two menu options are:

Cyclical Display and Event Display.







Maintenance Menu

Simulation

This menu is used to simulate the alarms for a particular sensor module or to temporarily activate one or more relays (or outputs). After exiting the simulation menu, the sensors and relays (excluding LS and HS relays) revert to their prior state.

Enter the access code by using the $[^{\land}] [\checkmark]$ and $[^{\blacktriangleleft}] [^{\triangleright}]$ keys.



© 0000 access

Sensor simulation

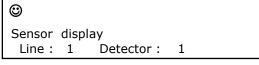
Select the sensor module you wish to test. Next, select the delay between each of the alarms to be activated (1-59 sec.). Validate your selections by pressing [\mathbf{OK}].

The central controller will increase reading levels until they exceed the thresholds for all activated alarms in ascending order +/- hysteresis. During the simulation, the theoretical values are displayed on screen.

During this phase, the other sensors are shut down. However, forced-state lines, modules and relays remain active.









Relay Status Simulation

Select the relay module for the relay you wish to test, then the relay you wish to activate.

Use the same "Relay Status" menu to select a relay. After pressing

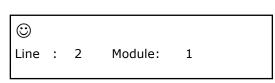
[**OK**] to select the relay, you have three options:

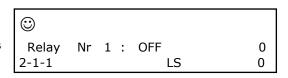
< Normal > = Relay functions normally (triggered by alarms)

< ON > = Relay in forced operation
(can only be shut down by a logic input)
< OFF > = Relay in forced shut-down
(can only be shut down by a logic input)

After exiting this menu, the relay will revert to its original state.







Analog Output Simulation

Module Verification

Inspection of all of the parameters relating to a module with a *communication fault*.



Module Control



Line: 2 Module: 1 ON CPS 10 CO niveau-1

4

E = Status word

D = Fault word

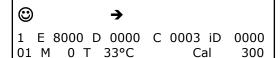
C = Start-up config. word

M = Level for sensor modules or State for logic inputs

T = Temperature

Cal (Value) = Concentration of gas used for calibration

ID = Module fault



Displays useful variables and operating time according to the module type:

(Value) = line voltage

R = Relay status (hexadecimal)

(Value) J = Number of days since last calibration.

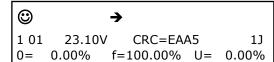
0 = X0 for sensor modules.

f = Xf for sensor modules.

U = Wear rate for sensor modules.

CRC = (Cyclic Redundancy Check)

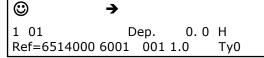
Software version for the module program.





Dep. (value) H = Time (in hours) during which the sensor exceeded the scale.

Ref: (Value) = Sensor reference.

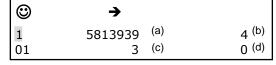


Retry: (plural form, *retries*) – attempt(s) at retransmission. Used to control the quality of communication with the modules.

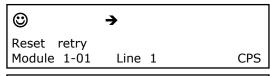
(a): represents successful transmission attempts. This number increases continually and should be as large as possible.

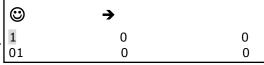
(b), (c), (d): represents next 3 successive retransmission attempts, if necessary, following a failed attempt. In the event that the 1st attempt (1) fails, a 2nd attempt (b) will occur, then a 3rd (c), and 4th (d). The number and the level of saved attempts is indicative of the transmission quality. A large number, on level 3 or 4 is due to poor transmission.

Reinitialize "retries" by selecting the "Reset retry" menu.



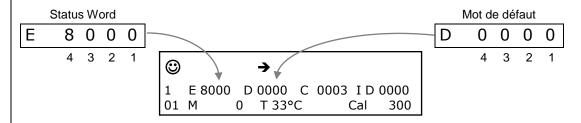






Any module fault generates an event, which is identified by a number (hexadecimal coding) corresponding to the fault type. The number at the end of the second line displays the module error.

The [◀] [▶] keys can be used to change the scroll mode: in normal mode, all events saved to memory are displayed; in default mode, only the faults saved to memory are displayed.



Fault word

4	3	2	1
1 = Def Flash	1 = Def Temp. Min	1 = Def Zero calibration	1 = Def ROM main memory
2 = Def sensor	2 = Def Temp. Max	2 = Def Sens. calibration	2 = Def RAM
4 = Low line power	4 = Def Meas. Min	4 = Def Zero Sensor replacement	4 = Def Battery
8 = high line power	8 = Def Meas. Max	8 = Def Sensitivity. Sensor replacement	8 = module parameter does not correspond to the module card

Sample fault word: 00A0 = Def Sens. calibration + Déf Sensitivity. Sensor replacement (A = 10 in hexadecimal = 8 + 2)

Status word

4	3	2 *	1
1 = BitEtatLiss	1 = BitEtatChg	1 = BitEtat0	1 = BitMod0
2 = BitJbFill	2 = BitEtatPar	2 = BitEtat1	2 = BitMod1
4 = BitJbDelay	4 = BitJbWait	4 = BitEtat2	4 = BitMod2
8 = BitEtatCell **	8 = BitJbCar	8 = BitEtat3	8 = BitMod3

**: only for sensor module (indicates presence of a sensor)

2 *	Status
0 (EtatMes)	Normal measure
BitEtat0 (EtatStab)	Stabilization
BitEtat1(EtatZInit)	Zero init
BitEtat0 + BitEtat1 (EtatStab)	Zero Stabilization
BitEtat2 (EtatZVal)	Zero validation
BitEtat0 + BitEtat2 (EtatSWait)	Sensitivity waiting
BitEtat1 + BitEtat2 (EtatSInit)	Sensitivity init
BitEtat0 + BitEtat1 + BitEtat3 (EtatSStab)	Sensitivity stabilization
BitEtat3 (EtatSVal)	Sensitivity validation
BitEtat0 + BitEtat3 (EtatChg)	Button replace pushed

Мо	odule Designation	Туре
1	Sensor CO	0
2	sensorNO	1
3	Sensor NO ₂	2
4	Sensor EXPLO	3
5	Sensor O ₂	4
6	Free	5
7	Free	6
8	Other	7
9	4 relay mod	8
10	8 relay module	9
11	Free	Α
12	Free	В
13	4ana output mod	С
14	16 log input mod	D
15	Analog input mod	E
16	Free	F

Bus Faults

This menu displays the faults from all modules in a line. Each hexadecimal number corresponds to a module, with Module 1 being on the left, and Module 32 on the right.

0 = OK

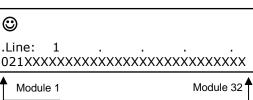
1 = Communication error

2 = Module recognition error

4 = Fault triggered by a module fault word.

X = module missing or unrecognized due to a conflict with another module





Line: 1 Module: 1 = OK

Line: 1 Module: 2 = module recognition error Line: 1 Module: 3 = communication error

Reset maintenance

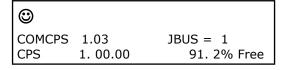
1 Reserved for ISC- maintenance personnel only.



CPS / COM_CPS Version – Available memory level

Displays the CPS central controller version as well as the COM_CPS programming software version.

Displays the microcontroller availability (time) rate (in %). This value will vary somewhat in relation to the program but can detect if a microprocessor is being overtaxed.



Enter the access code by using the $[^{\blacktriangle}][_{\blacktriangledown}]$ and $[^{\blacktriangleleft}][_{\blacktriangleright}]$ keys.

Next, press the [**OK**] key to reinitialize all counters to zero and to refresh the date.

|© |

0000 acces

CPS Installation

This menu is used to zero the following two settings across all modules: Last zero date

| 6

Installation CPS 26 / 06 / 07

Operating Time

Each module logs its operation time in days. For the sensors, this time is equal to the time since the last calibration or the last zero.

Exceeding the scale

Each sensor logs the amount of time that levels exceed the scale in seconds. Go to the "Module Verification" menu to see this time.

Chapter 6 Maintenance

Program transfer

This chapter describes the transfer of data from the COM_CPS application to the CPS, and vice versa (see the COM_CPS user's guide). After launching the software, you will see a welcome window.

PC → CPS transfer

Once the program has been created, the central controller should receive new settings...

Step 1: establish a physical connection

- Use either the USB or RS-232 adapter to connect the PC to the CPS central measuring controller.
- 2) Ensure that the CPS central measuring controller is connected to a power source.
- 3) On the central controller: flip the programming switch to the "MEM" position. The message "Switch open Program..." will appear on the display screen. Communication with the central controller is authorized during this phase..

Step 2: link configuration

- 1) In the menu bar, select [Communication > Port].
- Select the port [COM x] to use on the PC.

Note: communication speed is selected automatically

Step 3: data transfer

- In the menu bar, select [Transfer > from PC to CPS]. The message "Flip switch to MEM position in order to reprogram the central controller" refers to the <MEM> position on the CPS central controller commutator before starting the transfer procedClick [OK] once verification has ended.
- 2) During the transfer, a progress bar will indicate transfer progress.
- Once the transfer is complete, the message "Operation complete" will appear on screen. Click [OK]. The configuration program has been transferred from the PC to the CPS central controller.
- 4) On the central controller: The message "Switch open Complete" will appear on the display screen. Flip the programming switch to the "Prog" position.
- 5) The central controller will perform a "Start-up" procedure.

CPS → **PC** transfer

Step 1: establish a connection

- 1) Use either the USB or RS-232 adapter to connect the PC to the CPS central controller.
- Ensure that the CPS central measuring controller is connected to a power source.
- 4) On the central controller: flip the programming switch to the "MEM" position. The message "Switch open Program…" will appear on the display screen. Communication with the central controller is authorized during this phase.
 - Or, use the "Control" menu to set the printer to "OFF."

Step 2: link configuration

- 1) In the menu bar, select [Communication > Port].
- Select the port [COM x] to use on the PC.

Note: communication speed is selected automatically.

Step 3: data transfer

- 1) In the menu bar, select [Transfer > from CPS to PC].
- 2) The message, "Do you want to read the CPS central controller configuration?" will appear onscreen. Click [OK]. If the message, "Check port configuration and ensure printer set to OFF position and try again" appears, verify that the CPS printer is in the OFF position.
- Select the folder where you want to download the file, and create a file name (a default name is suggested).
- 4) During the transfer, a progress bar will indicate transfer progress.
- 5) Once the transfer is complete, the message "Operation complete" will appear on screen. Click [OK]. The data has been transferred from the CPS central controller to the PC.
- 6) **On the central controller**: The message "Switch open Complete" will appear on the display screen. Flip the programming switch to the "Prog" position.
- 7) The central controller will perform a "Start-up" procedure.

Error messages

Error messages will appear in the following scenarios:

ERR 01: Module fault relating to the program.

The test runs systematically on start-up and periodically when a module is activated by the menu if the module does not correspond to the loaded program. The error remains until the problem is corrected or until the module is shut down.

ERR 02: Fault word reading for a module. Name displayed on the 1st line of the screen.

ERR 04: Power line error.

ERR 08: I2C (real-time clock) or EEPROM error.

ERR 10: Module communication error.

ERR 20: Problem originating at printer. Printer shut-down or lack of paper.

Checksum error

When the central controller starts up, checksum values appear briefly on screen after the display test. The value calculated by the central controller is displayed on the first line, and the checksum calculated by the PC with the COM_CPS software is displayed on the 2nd line.

If these two values are different, this screen will remain on the display screen, indicating that there is a problem (example: depleted battery.) The user program protection switch must be flipped, and a new COM_CPS program must be transferred.

Flip the switch back into the "closed padlock" position before restarting the central controller.

Example of an error

Operation before event

 \odot

CPS

Parking

CPS Analysis Parking Charles de Gaulle 21:04

Technical alarm triggered (fault). buzzer engaged (if activated), Front panel yellow LED illuminated. Two pictograms appear: the blinking "maintenance key" and the "siren."

Air

CPS Analysis Parking Charles de Gaulle

Analysis

21:04

Action on the front panel "acknowl" button. Audible alarm (buzzer) is off.

"Siren" pictogram disappears.

"Maintenance key" pictogram remains on screen. Front panel yellow LED illuminated.

Charles de Gaulle

21:07

Action on the "acknowl" button.

Direct access to the "ERRORS" data page.

ERR 11 = ERR 10 + ERR 1

Communication fault for Module 1, Line 2.

Check the line and/or the module. The fault will disappear when the problem is resolved.

py module level 1

Relay module level-1 ERR11 : Com. 2 01

If multiple errors occur, all of the error codes will be displayed one after another. The faulting modules for each error will be displayed one at a time by their line number and module number.

For all faults except for communication faults, the gas level will be displayed in order to help the user identify the problem.

41

Sensor CO 1, level-1

ERR01 : Type 2 01

Meas=x.x

Testing and calibration of stable installations

Warning: The setting of this section are reserved for authorized persons formed because they might call into question the reliability of detection.

The site responsible is required to establish security procedures on its site. OLDHAM may be not responsible for their implementation.

Gas detectors are above all safety instruments. In consideration of this, **OLDHAM** recommends regular planned testing of fixed gas detection installations.

A functional test involves injecting a sufficient concentration of gas at the sensor level to trigger preset alarms. This test does not replace a full sensor calibration under any circumstances.

The frequency of gas tests depends on the industrial application in which the detector is in use. Frequent inspections should be made in the months following the commissioning of the installation, and then become more widely spaced provided that no significant deviation is observed.

If a detector should fail to react when in contact with the gas, calibration is essential. The frequency of calibrations is a function of the results of the tests (humidity, temperature, dust, etc.). However, it must not exceed one year. It is also advisable to calibrate the sensor after exposure to high concentrations of gas.

. Gas concentration which must be used during manual or semi automatic calibration

- CPS 10 CH4 = 2.5% CH4/air
- CPS 10 H2 = 2% H2/air
- CPS 10 C4H10 = 0.9% C4H10/air
- CPS 10 **CO** = 100ppm
- CPS 10 **NO** = 50ppm
- CPS 10 NO₂ = 10ppm

Sensor replacement

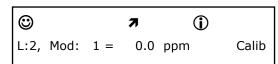
Sensors should be replaced as a part of regular preventative maintenance or following a failed calibration test.

After replacing a sensor, a calibration test must be conducted (see the chapter on semi-automatic calibration).

To replace a sensor:

- Remove the sensor cover.
- Hold down the sensor replacement button (1) for 5 seconds, until the solid green LED (2) is on.
- Release the button.
- Replace the sensor and conduct a calibration test (mandatory) according to the semi-automatic procedure.

On the central controller, the "maintenance key" pictogram indicates that the sensor has been replaced. The key will remain on screen until the sensor has been calibrated or until the sensor's power supply fails. The wear settings for the sensor are initialized upon calibration



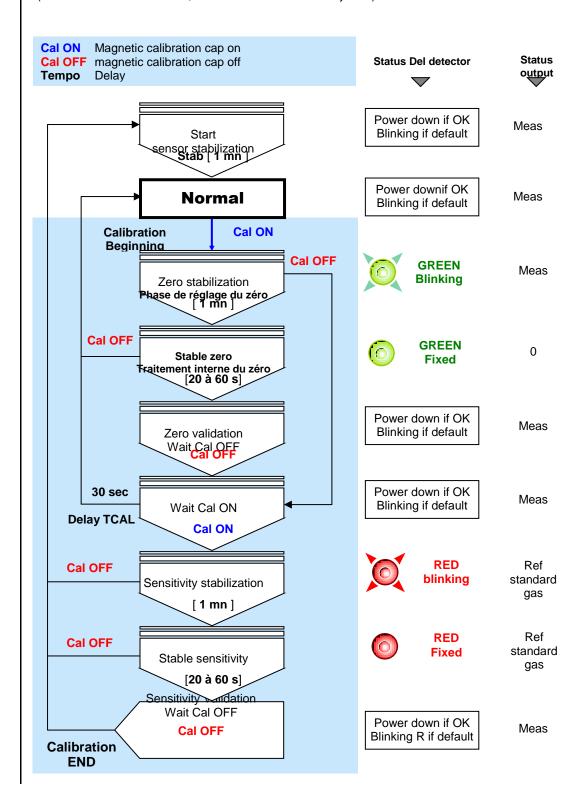
Semi-automatic calibration

During a sensor module calibration, the central controller blocks the alarms from the module in question and displays a maintenance key on the screen. Up to 10 sensors can be calibrated at the same time. The concentration level for the calibration gas is stored in the sensor's memory.

Each calibration start and stop is logged as an event.

The printer records a state after the calibration of each sensor (cf : Printing).

If the calibration is failed, the sensor is listed as faulting and an event is logged with a fault code (0010 - calibration zero fault, 0020 = calibration sensitivity fault).



Manual calibration

The calibration kit provided by ISC must be used (Ref. 6 116 291) female connector / wires / voltmeter connection files).

- Remove the sensor cover.
- Connect the cable (strand) to the circuit's male connector.

Zero adjustment

Ensure that the sensor is in clean air. If not, inject air into the sensor at a flow rate of 60 l/h, then wait for voltmeter levels to stabilize (use the gas injection device: bottle of synthetic air, calibration pipe, tube).

- Adjust the zero with the potentiometer's "ZERO" until the voltmeter reads 0 mV.

Sensitivity adjustments

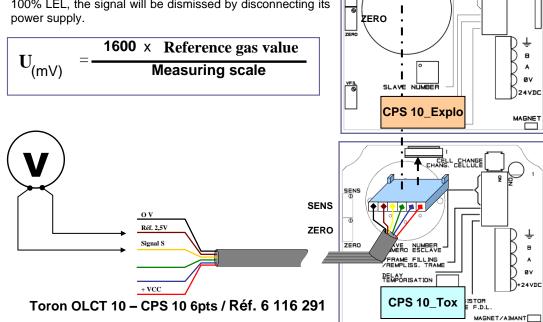
- Now inject the known gas (60 l/h) into the sensor, and wait for the voltmeter signal to stabilize.
- Adjust the sensitivity if necessary with the potentiometer "SENS" until the signal value (in mV) corresponds to the amount of reference gas used. Use the following formula to calculate the correct value for the signal.

\$ENS

- Stop injecting gas (remove the calibration pipe from the sensor).
- Wait for the voltmeter to "return to zero."

Version CPS 10 for explosive gas

The CPS central controller has a "**verification**" function: if the sensor measures a concentration of gas higher than 100% LEL, the signal will be dismissed by disconnecting its power supply.



MAINTENANCE WIRES:

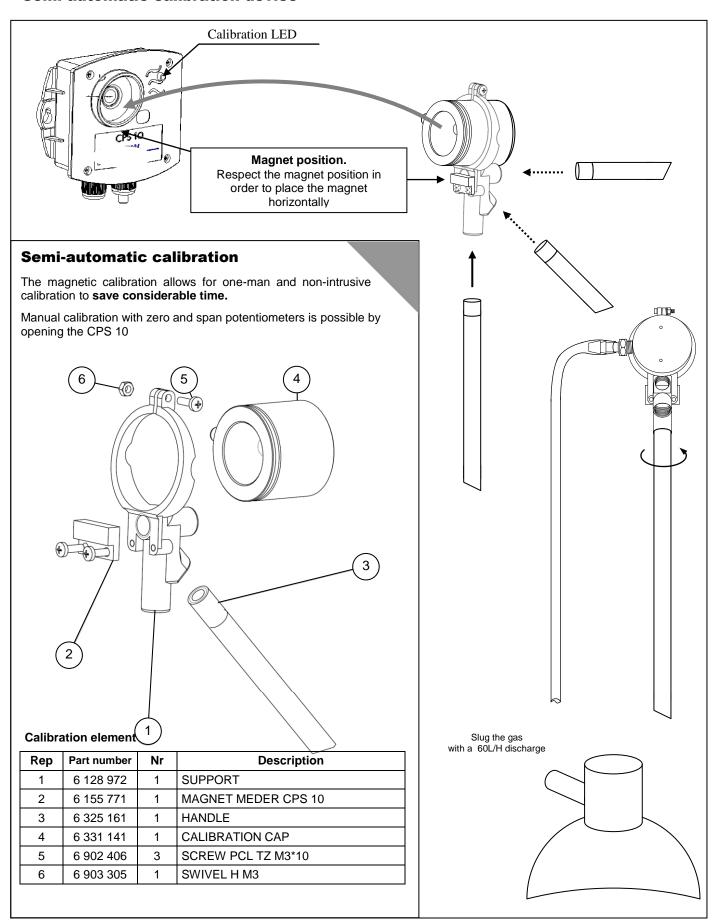
+VCC (red) = + power supply

Signal S (yellow) = signal from 0 mV to 1600 mV for zero and sensitivity measure Ref 2,5V (brown) = zero reference for signal reading from 0 mV to 1600 mV

GND (**black**) = electronic circuit ground.



Semi-automatic calibration device



Central controller maintenance

Do not use alcohol- or ammonia-based liquids to clean the central controller. If necessary, clean the exterior of the central controller with a damp cloth.

Lithium battery

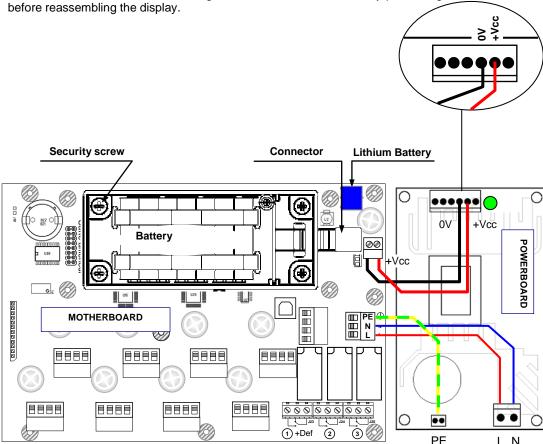
If the central controller configuration settings are lost, the lithium battery soldered to the display card must be replaced. This operation should be performed by a qualified professional.

Lithium battery characteristics: VARTA CR1/3N or equivalent.

Back-up battery pack

When the back-up battery power drops, the battery should be replaced. This operation should only be performed by a qualified professional.

The battery pack is located underneath the display screen on the wall-mounted version. Take off the display screen to access the battery pack. Unplug the connector linking the battery pack to the motherboard. Remove the 4 mounting screws. Attach the new battery pack. Plug in the connectors



Scrapping of CPS System

Concerning the conservation, of the protection and the improvement of the quality of the environment, as well as for the protection of the health of the persons and the careful and rational use of natural resources, CPS system has to be the object of a selective collection for the electronic equipments and cannot be scrapped with the normal domestic waste. The user thus has the obligation to separate the CPS system of the other waste so as to guarantee that it is recycled in a sure way at the environmental level. For more details of the existing sites of collection, contact the local administration or the distributor of this product.



Chapter 7 Technical Specifications

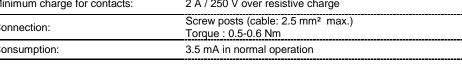
	<u>.</u>
CPS Central Contro	oller
CPS w/ metal wall-mounted casing:	Dimensions (mm): 320 x 180 x 95
	Degree of protection: IP 54
Cable entries	5 M20 cable glands Diameter 5-12 mm power / local relays 9 PG9 1 D-SUB 9 Pin RS-232 cable
CPS rack version	Dimensions: Length: 19"; Height: 4 U (176 mm) IP class: IP 31
Operating conditions	
Ambient temperature:	-10°C to 40°C
Storage temperature:	-20°C to 85°C
Humidity:	5 to 95% noncondensing
Power supply	
Mains power supply:	Voltage: 110-240VCA
Battery back-up:	Optional – Capacity: 600 mAh
24 V Consumption:	140 mA + 12 mA per measurement line (240 mA max.)
Measuring lines	
Number:	8 RS-485 digital measuring lines
Line capacity:	32 digital CPS modules (CPS 10,CPS RM, CPS DI16, CPS AO4) ModBus Protocol
Cable type:	2 twisted pairs shielded RS-485 4Xawg22 (diameter 0.67mm) cable, 100 $\!$
Transmission speed:	9600 Bauds (trial with 0.35 mm²)
Module power supply:	12 to 30 VCC via the CPS central controller and if necessary via a 24VCC external additional power supply
Digital module network:	RS-485 ModBus, addresses 1 to 32, set with mini switches
Isolation:	Power supply / Digital network: 1500 V
Display	Backlit LCD display [2 lines, 32 characters per line - 1 line for pictograms - 3 electroluminescence diodes to indicate operating status: OK, Fault, Alarms]
Keyboard	Membrane keyboard, 7 intuitive keys
Local buzzer	Alarm and fault signaling
Integrated printer	Optional for rack version (no integrated printer option for the metallic wall casing)
Alarms	
Number of alarms:	6 alarms per sensor (AL1, AL2, AL3, AL4, Out of Range, Fault + Validation for Explo gas)
Programmable thresholds:	For instantaneous or averaged values, increasing or decreasing values, or for manual or automatic rearming.
3 Internal local relays	Relay: R1 (alarm/fault) – R2 (alarm) – R3 (alarm). Minimum charge for RCT contacts: 2A / 250 VAC – 30 Vcc (resistive charge) Relays settings are configured with the COM_CPS configuration software. Torque: 0.5-0.6 Nm
Centralized supervision system digital of	·
RS-485	ModBus Protocol (connection with a centralized supervision device)
RS-232 or USB	USB protocol priority (permanent connection to system configuration)
Approvals:	
Low Voltage Directive:	This device is in compliance with the security requirements of Directive 73/23/EEC, modified by Directive 93/68/EEC, based on standard 61010-1 and its second amendment.
Metrology:	Underground parking facilities: according to VDI 2053
EMC Electromagnetic compatibility:	according to EN 50270

CPS 10 Sensor N	/lodule
Dimensions (mm):	118 x 110 x 60
Degree of protection:	IP 54
Cable entries:	2 M16 cable glands 4-8 mm diameter
Consumption:	Toxic gas sensor: 2.5 mA in normal operation Explo gas sensor: 50 mA in normal operation
Status indication after calibration	Red/Green electroluminescent diode
Calibration:	Automatic, no need to open the sensor due to a gas introduction device equipped with a magnetic switch, or with a potentiometer inside of the case.
Sensor replacement:	Sensor replacement switch on the interior of the CPS 10 case. Detection of sensor



CPS R	RM4 or	RM8	Relay	Module
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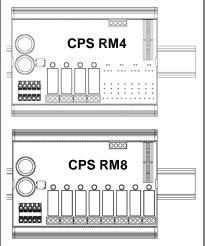
Dimensions (mm):	125 x 165 x 60
Mounting:	Ratchets into DIN rail
Number of relays:	4 relays (CPS RM4); 8 relays (CPS RM8) Contact type: RCT
Minimum charge for contacts:	2 A / 250 V over resistive charge
Connection:	Screw posts (cable: 2.5 mm² max.) Torque : 0.5-0.6 Nm
Consumption:	3.5 mA in normal operation



Bistable Relays.

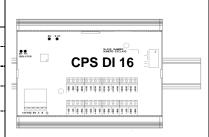
Configuration of positive or negative relay security with mini switches. Relay modules have 2 logic inputs.

Configuration via the COM_CPS configuration software.



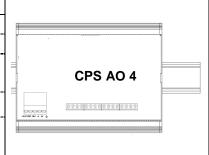
CPS DI16 Logic Inputs Module

	-	ı
Dimensions (mm):	125 x 165 x 60	ì
Mounting:	Ratchets into DIN rail	=
Number of All or Nothing Inputs:	16	 ı _
Connection:	Screw posts (cable: 1.5 mm² max.) Torque: 0.5-0.6 Nm	=
Consumption:	2 mA in normal operation	



CPS AO4 Analog Output Module

		ì
Dimensions (mm):	125 x 165 x 60	
Mounting:	Ratchets into DIN rail	ı
Number of analog outputs:	4-20 mA output, max. resistance 500 Ω Isolation galvanique individuelle + 2 entrées logiques	
Connection:	Screw posts (cable: 1.5 mm² max.) Torque : 0.5-0.6 Nm	=
Consumption under 24V at module input	I< 5 mA if the 4 channels are shut down I< 36 mA if only one channel is activated I<130 mA if all 4 channels are activated	Ī



Chapter 8

Annexes

JBUS/MODBUS Protocol

JBUS Transfer Table

A RESS Classification is automatically made by the COMCPS in the ascending order of the relays then modules then lines.

Nota: Relays and inputs are numbered from 1 to 256 and from 1 to 64 in order to optimize the occupation memory in the CPS

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-	0001	Illne, Alarm 1 Status of each detector module Module	2 hytes	L1, M32	L1, M31	L1, M30	11. V29	-1, L vos IV	1, L	1, L1 26 MC	35 MB	1, L1, 124 MB	1, L1, 123 MZ	, L1,	L1, 1 M.X	L1, M48	L1, N 18	L1, M17
	0002		2 bytes	- M	- ≌	- 5	- 2		- E	- 8 - 8			8	58	= ₹	Ξ≅	- 2	5.≥
8	0003		2 bytes		L2, M31	_	L2, M29	12, LZ NZ8 M	L2, L3 M27 M	2, 12 M26 MC	_	L2, L2, NZ4 MZ3	. 12. 23 MZZ		1. M.20	L2, M19	_	L2, M17
¥	0004		2 bytes	L2, M16		L2, M14						_	_	. L2		_	Ľ2.	L2, M1
			2 bytes				П	H	H	H	H	H	H	H	H	L		
15	900E		2 bytes	L8,M		18,M 30	W'87	N	М	18,1M L8,1 25 25	,ML8,h	8,M L8,	,M L8,1	M L8,	N 5.0	V	N.8.1 18	L8,M 17
16	0010		2 bytes		15,0 15	5	5	08,M D	13,ML	2	М	_	5	3	М	ME8,6	18.7 2	L8,M 1
17	0011	Arm 2 Status of each detector module Module	2 bytes	L1, M32	L1, M31	L1, N30	L1, I M29	L1, L' NZ8 M	L1, L' M27 M	L1, L1 M26 M3	11, L1 N25 M2	L1, L1, N24 M23	, L1, 23 MZZ	, L1, 2 M21	L1. M20	L1, M19	L1, M18	L1, M17
	-					П	П	H	H	Н	Н	Н	Н	Н	Н	Ц	Ц	
33	0021	Alarm 3 Status of each detector module Idem				П	П	Н	Н	Н	Н	Н	Н	Н	Н	Ц	Ц	
69	1600	Aarm 4 Status of each detector module lidem				П	П	H	H	Н	Н	Н	Н	Н	Н	Ц	Ц	
99	0041	Alarm overscale. Status of each detector module				П	П	Н	Н	Н	Н	Н	Н	Н	Н	Ц	Ц	
81	1900	Aarm fault Status of each detector module Idem				П	П	H	Н	Н	Н	Н	Н	Н	Н	Ц	Ц	
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B# 3	Shysien	82/elen					l
† 1E	c i yelen	es/elen	***			•••	l
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9 18	g pág ja	relayat					l
£ 18	a hysia i	relaysz	***				l
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Z 18	relay3	elyalei					
£ 18	telay4	relay20					
t 18	aysien	rsiayzı					
9 1E	elay6	SZýslen					
918	7\psien	relay23					
£ 18	Relays	relayat					
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			П	Ш	П		
			П	П	П	П	l
			П	Ш	П		
			Н	Н	Н	Н	l
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S S/E	elays 1-8	817.5	lays 33-4	relays 49-56	8	elays 240	0 = 3KQ
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76	97	86	66	8	Þ	112	113

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113	1,700	Module Fault																	H	l	
113	1,700	line fault		ine Bulti	тодие 2	Faut type for the both modules				enilgrithate Eur Eu	TM, FLI Allm Ins TM, FLI	eluborninatni Lit , Mit	Module type L1,M1 Communicatio	u			enlignthete SM, tu ent milA	ZM, ra L1, M2 Intern module	Module type L1, M2	L1, M2 Communicatio	ц
114	2/00	line fault	ε епрош	me tautti		mebi	2 bytes	H	H	L	L	L	H	H	L		F	H	H	L	Г
115	8700		П	The Buff1	9 апрош	nebi	2 bytes	H	\vdash	H	L		H	\vdash	H		T	H	Н	H	
116	0074	line fault1		line fault1	module 8	Idem	2 bytes														
117	0075		module 9	line Bult1	module 10	Idem	2 bytes		H	Ц				H				H	Н	Н	
								Н	H	Н	Ц		Н	Н	Ц		d	Н	Н	Н	
128	0800	line fault1	1	line tault1	module 32	Idem	2 bytes	Н	H	Н	Ц		Н	Н	Ц		H	H	Н	Н	
129	0081	line fault2	module 1	line Bult2	module 2	idem	2 bytes	\dagger	\dashv	\dashv	\coprod		\dagger	\dashv	\downarrow			\dashv	\dashv	\dashv	П
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145	1800	line fault3	module 1	ne auts	module 2	Idem	2 Dytes	\dagger	+	+	4	1	\dagger	+	\downarrow	1	<u> </u>	+	+	+	Т
181	0081	line fault4	module 1	The Buffd	module 2	Idem	2 bytes	\dagger	+	+	\downarrow		\dagger	+	\downarrow	\perp	T	+	+	+	Τ
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111	00B1	line fault5	module 1	lne tault5	module 2	Idem	2 bytes	H	\vdash	\vdash	L		T	\vdash	L		T	H	H	H	П
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193	00C1	line faul6	module 1	ine tauttis	module 2	idem	2 bytes	H	H	Н	Ц		Н	H	Ц		Ħ	H	Н	Н	
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209	00D1	line faul?	module 1	ne aut7	module 2	Idem	2 Dytes	\dagger	+	+	4		\dagger	+	4	1		+	+	+	Т
338	0051	line fault8	modula 1	Pro faults	module 2	mejori	2 Profess	†	+	+	4	I	†	+	\downarrow	\prod	İ	\dagger	+	╀	Т
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240	0000	line fault8	module 31 The faut8	ne auts	module 32	Idem	2 bytes	t	+	╀	╀	I	t	╀	ļ	I	T	\dagger	╁	╀	Т
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241	00F1	forced operating.																			
241	00F1	relay 1-8		relay 9-16			2 bytes	System					Zýsjeu				relay13	relayî 2	relayî î		e(slet
242	00F2	relay 17-24		relay 25-32			2 bytes	talei	ह्य (ब्र <u>ब</u>	SSystem	rsysien Osysien	61५वन	8f एखना	Thysien	SSYBIEN PSYBIEN	те (втег	es/elen	82\elan	TSysien TSysien	9Z/EIBI	ela)Z5
243	00F3	relay 33-40		relay41-48			2 bytes					""									""
244	00F4	relay 49-56		relay 57-64			2 bytes	=				""				::	***				***
245	00F5	relay		relay			2 bytes					***	***			:	***				***
256	0100	relay 240-248 relay 249-					2 bytes					""	***			:	***				""
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5 8 8			Module 1		ПΠ	4 bytes (32 bits not signed)
8 8	overscale delay	8 94	Module 32		2 bytes 2 bytes	4 bytes (32 bits not signed)

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30543	47.7		Lea I	Module 31	П	2 bytes (16 bits not signed)	
30544	7750		line 1	Module 32	Т	2 bytes (16 bits not signed)	
30545	7751		Te 2	Module 1	T		
30546	7,162	latest calibration	lle 2	Module 2	WOR	Z Bytes (16 Difs Not Signed)	
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30609	1877	latest calibration	lne 4	Module 1	Word	2 bytes (16 bits not signed)	
30641	7781	latest calibration	9 8 9	Wodule 1	Word	2 bytes (16 bits not stoned)	
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30673	77D1	latest calibration	line 6	Module 1	Word	2 bytes (16 bits not signed)	
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2000]			Ť	-1	
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30769	7831	latest calibration	o au	MODURE 32	WOR	Z Dyles (16 DIS not signed)	
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						18 18 18	18 18 18
Source	1.007	Politica of flex event to be lecon	noed (Illoddo).	(000	WOO	Z IVIES (16 DIS INI SIB RU)	
30770	7832	(-1 if the system doesn't receive its	its 1200 events	,	Word	2 bytes (16 bits not signed)	
30771	7833	Pointer on event to be printed			Word	2 bytes (16 bits not signed)	
30770	7834	EMPTV				7 1116 3 1116 4 1117 4 1117 5 1117 11 117 1 117 1 117	7 111 3 111 3 111 4 111 5 111 5 111 1 111 1 1 111
30808	7859	event					
30809	7859	event N				Day	Month
30810	785A	event N					Hour
50611	900/	event N					Seconds
30813	188D	evert N				Extra Information	Extra Information
30814	785E	evert N+1			Ī		Month
30815	3987	event N+1					Heure
30816	0987	event N+1					seconde
30617	7861	event N+1					Event number
30618	7,997	event N+1				Extra information	Extra Information
36807	8FC7	event N+1199				Module number	No event
36808	SFCS	event N+1199				JU.	Extra Information
36810	8FCA	on the last printed		(Modulo 4)	Word		
36811	8FCB	80 byte					
36971	8068	Test M + 2 80 hv/a fest			T		
37051	8088	80 byte					
					$\left \right $		

					-	3yle1 Byle2
					_	
	9					21 III 21
10000	JBUS	Delegate model rose			T	
40001	9C41	Instantaneous messure	i eri	Module 1 1 V	Word	2 Mes (18 bits not streed)
40002	9C42	Ī	Te 1	2	Γ	
40003	9C43	T	Te 1		Γ	2 bytes (16 bits not signed)
40004	9C44	f	Te 1	Wodule 4	Γ	2 bytes (16 bits not staned)
40005	9C45	T	Te 1		Г	2 bytes (16 bits not storned)
		1			T	
40028	9050	Instantaneous measure	ne 1	Wodule 28	Word	2 bytes (16 bits not slaned)
40029	9050	Ť	Le 1		Т	
40030	9CSE		Te 1		Т	41-
40031	9CSF		Te 1		Т	bytes (
40032	9C60	T	T er		Т	2 bytes (16 bits not stoned)
40033	9061	T	ne 2		Т	2 bytes (16 bits not signed)
40034	9062	T	The 2		Γ	
		١			Γ	
40065	9C81	Instantaneous measure	ne 3	Module 1	Word	2 bytes (16 bits not signed)
					П	
40097	9CA1	Instantaneous measure	lne 4	Module 1	Word	2 bytes (16 bits not signed)
00000		ľ			T	A broken of all the conductions of
40129	LOOR	Installaneous measure	0 00	Module 1	WOR	2 Dytes (16 DIS not signed)
40161	9CE1	Instantaneous measure	De 6	Wodue 1	Word	2 bytes (16 bits not stared)
		1			T	
40193	9001	Instantaneous measure	lne 7	Wodule 1	Word	2 bytes (16 bits not signed)
		ľ			7	
40225	9D21	Instantaneous measure	Le S	Module 1	Word	2 bytes (16 bits not signed)
40256	9D40	Instantaneous measure	ne 8	Module 32	Word	2 bytes (16 bits not signed)
Ī	FPU6	1			1	
40004	1	-				
					_	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
						8tt 8tt 8tt 8tt 8tt 8tt 8tt 8tt 8tt 8tt
40257	9D41	4-20mA Outputs Value (1000 = 1	1mA)			
40257	9D41		output		7	2 bytes (16 bits not signed)
40258	9D42	value	Outputs		7	pytes (
40209	9D43		oulpurs		T	2 pytes (16 pits not signed)
40260	9044	Output4-20mA Value o	output4		Word	
4,0000	8049		outhrip		Ť	
40002	9040		outputs		T	Z Dytes (16 Dits Filt Signed)
40003	904/	Output4-20m4 Value	output		T	Z Dytes (16 Dits FRI signed) 3 hidse (18 hits not storned)
40004	0000	ľ	outra do		T	Spiros (19 bits not element)
90000	8048	ľ	cultura		T	Z Výtes (10 Vís IV) Slýteu) S kulos (10 kilo sek stemost
40087	arus	Output-20m8 Value	outrath1		Word	2 pytos (10 bila military art)
40068	DPU6	Ī	outst42		T	-1-
00000+	2500	1	output iz		T	(name interest and a series
40612	9E40	Output4-20mA Value o	output256		Word	2 bytes (16 bits not staned)
40613	9E41				1	

Dééctor messures Modité 1 Averaged messure 2 Ine 1 Modité 1 Averaged messure 2 Ine 1 Modité 1 Averaged messure 3 Ine 1 Modité 1 Averaged messure 2 Ine 2 Modité 1 Averaged messure 2 Ine 2 Modité 1 Averaged messure 1 Ine 3 Modité 1 Averaged messure 1 Ine 3 Modité 1 Averaged messure 1 Ine 5 Modité 1 Averaged messure 1 Ine 6 Modité 1 Averaged messure 1 Ine 6 Modité 1 Averaged messure 1 Ine 8 Modité 1 Averaged messure 1 Ine 8 Modité 1 Averaged messure 1 Ine 8 Modité 2 Averaged messure 1 Ine 1 Modité 2 Averaged messure 1 Ine 1 Modité 3 Average messure 1 Ine 1 Modité 3

	Snar		21 118 21 118 21 119 11 118 21 119 8 119	3116 3116 3117 3117 3110 3110
44793	A341	District measures		
41793	A341	Senierret	Byte1	Byte2
41794	A342	Sentence1		Byte4
11795	A343	Sentence1		Bytes
11796	A344	Sentencet		Byte8
41797	A345	Sentence1		Byte10
11797	A345	Sentence		Byte12
41798	A346	Sentence1		Byte14
11799	A347	Sentence1		Byte16
41800	A348	Sentence1		Byte18
11801	A349	Sentencer	Byte19 By	B)te20
11801	A349	Sentence1		Byte22
41802	A34A	Sentement		Byte24
11803	A34B	Sentence1		Byte26
41804	A34C	Sentement		te28
1805	A34D	Sentencer		Byte30
11806	A34E	Sentence1		Byte32
41807	A34F	Sentence1	Byte33 / term at the end of the sentence By	Byte34 / empty
41808	A350		1	
			ᆫ	2: 5: 5: 9:
	JBUS		1181 1181 1181	811 811 811 811
1808	A350	Detector measures		
1808	A350	Sentieros2	Byte1 By	Byte2
1809	A351	Sentence2		B)te4
11810	A352	Sentence2		Byte6
41811	A353	Senterce2		Byte8
11812	A354	Senteros2	Byte9 By	Byte10
41812	A354	Sentence2		Byte12
41813	A355	Senterce2		Byte14
41814	A356	Sentence2		Byte16
41815	A357	Senterce2		Byte18
1816	A358	Sentence2		Byte20
41816	A358	Sentence2	Byte21 By	Byte22
11817	A359	Senterce2	Byte23 By	Byte24
1818	A35A	Senterce2	Byte25 By	Byte26
1819	A35B	Sentieroe2		te28
41820	A35C	Senteme2		Byte30
1821	A35D	Sentencez		BN632
41822	A35E	Sentence2	I term at the end of the sentence	Byte34 / empty
41823	A36F	Wind Indiana	1	
			11 12 13	3 9
			119 119 119 119 119 119 119 119 119	111 112 113 114 115 115 115 115 115 115 115 115 115
41823	A35F	Remoted keyboard Word		
41824	A360	Blank 32 bytes		
41855	A37E			

STORY OF THE PROPERTY OF	000000000			000
SELLINGS V	IN COMICES		e) in in in in in in in in in in in in in	Bilez
			ᆫ	21 21 21 21 21 21
	JBUS			
50001	C351	Module list		
50001	C351	Module 1 Name (32byte)	Byte 1 Name By	Byte 2 Name
		The state of the s		
50017	C361	Module type (1 byte) Relay position (1 byte)	Module type (1 byte)	Indice relay (1 byte)
50018	2382		(6	Config by fault (1 byte)
50019	සෙ	Module 2 Name (32byte)	Byte 1 name By	Byte 2 name
	0000			
50035	C373			Relay position (1 byte)
50036	C374	Input Position (1 byte) Config by faut (1 byte)	Input position (1 byte)	Config by fault (1 byte)
	0000	The state of the s		
54591	JE90	Module name 256 (32byte)	Byte 1 name	Byte 2 name
	0000			
54607	D54F			Relay position (1 byte)
54608	0990	Input position (1 byte) Config by fault (1 byte)	Input position (1 byte)	Config by fault (1 byte)
54609	D551			
	!		6: 01:1 21:1 21:1 91:1	0:: 21 21 21 21 21 21 21 21 21 21 21 21 21
	JBUS		18	18
54609	1990	Relaylist		
2,4000	1000	and but to the state of the sta	Charles of a contract of the contract	Relay number on the
54810	1000			Date 2 name
54620	D65C	HS position / function output4-20mA (1byte) empty Byte 2 bytes	HS position	
54621	0990	Module number (1byte) and Relay function and position (1b)	nber (0-255)	Relay function number Relay number on the
54622	D65E	Relay Name Joulput 2 (20byte) 2 bytes	Byte 1 name By	Byte 2 name
54632	D568	HS Position / function output4-20mA (1byte) empty Byte 2 bytes	HS Position	
		···		
57669	E145	position and function (1b)	er (0-255)	Relay function number Relay number on the
		Relay Name Joulput256 (20byte) 2 bytes	Byte 1 name By	Byte 2 name
		HS position /runction output4-20mA (1byte) Empty Byte 2 bytes	HS position	
57681	E161	_		

	5			21 11 21 11 21 11 11 11 11 11 2 1	41 41 511 511 511 611
57681	JBUS E161	Urbut list		88 88 88 88 88 88 88 88 88 88 88 88 88	8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8
57681	E151	Module number (1 byte) and input number (1b)	2 bytes	Module number (0-255)	Relay function number Relay number on the
57682	E152			Byte1 Name	Byte 2 Name
57692	E15C	Module number (1byte) and relay function and position (1b)	on (1b) 2 bytes	Module number (0-255)	Relay function number Relay number on the
57693	E15D	Input 2 name (20byle)	2 bytes	Byte1 Name	Byte 2 Name
60431	ECOF	and input number (1b)		Byte1 Name	Bytez Name
		Input 1 name (20 byle) rek	relay position (1 byte) 2 bytes	Module type (1 byte)	Relay position (1 byte)
60442	EC1A	_			
		DETAILS AND DADAMETEDS OF THE 10 TYPES	VEST OF BYSHIP I SENSODS ABSTRACTOR	(50)	
		DELONGO POPULIE EN OF THE 10 TIPES	or resident streets (Negery Foods)	(2.5)	
				0 Z 7	
	BUS			1 118 1 118 1 118 1 118 1 118	311 7 311 6 311 6 311 7 311 7 311 7 311 7 311 7
60462	ECZE	List units of the modules			
60462	ECZE	gaz name for type 1 (6 bytes)		Byte1 Name	Byte2 Name
60465	EC31	gaz name for type 2 (6 bytes)		Byte1 Name	Byte2 Name
00700	0	The state of the state of the state of			
60489	EC49	gaz name tor type 10 (s bytes)		Byte1 Name	Bytez Name
00000	0801				
28400	EC#C	_			
				11 11 12 13	8
	JBUS			. 18 . 18 . 18 . 18	18 18 18 18 18 18 18
60492	EC4C	Code of detector gas type			
60492	EC4C	Gas code for type 1 and 2 (2 bytes)		Code type 1	Code Type 2
60493		Gas code for type 3 and 4 (2 bytes)		Code type 3	Code Type 4
00700		The second for the second of the second		5	20 mm
60496		cas code for type 9 and 10 (2 bytes)		coe type 9	code Type 10
60497	ECS1	_			
				0 Z	
	BUS			18 118 118 118 118 118	18 1 18 1 18 1 18 1 18 1 18 1 18 1 18
60497	EC51	Instantaneous alarm threshold			
60497	EO51		ype 1 Word	_	
60498	EC52			2 bytes (16 bits not signed)	
60439	EC53	hstantaneous alarm 1 threshold Ty	Pype 3 Word	2 bytes (16 bits not signed)	
90909	ECSA			2 bytes (16 bits not signed)	
60607	ECSB			2 bytes (16 bits not signed)	
60909	2020	Installaneous agrill 2 threshold TV	Type 2 Word	2 bytes (16 bits not signed)	
60616	EO84	hstantaneous alarm 2 threshold Ty	Type 10 Word	2 bytes (16 bits not signed)	
00000	00001		Table 1997	Charles of the bull of the control of	
ocono	EUO	INTRINGUES ARTIN 4 UNESTON	Type 10	Z Dytes (10 Dits Not Signed)	

				2 E E E E E E E E E E E E E E E E E E E
	JBUS			118 118 118 118 118 118 118 118 118 118
60637	EC79	Averaged alarm threshold		
60537	EC79	Averaged alarm 1 threshold	Type 1 Word	2 bytes (16 bits not signed)
60638	EC7A	Averaged alarm 1 threshold	Type 2 World	2 bytes (
60938	EC7B	Averaged alarm 1 threshold	Type 3 Word	2 bytes (
				Г
60546	EC82	Averaged alarm 1 threshold	Type 10 Word	2 bytes (16 bits not signed)
60547	EC83	Averaged alarm 2 threshold	Type 1 Word	2 bytes (16 bits not signed)
60548	EC84	Averaged alarm 2 threshold	Type 2 Word	2 bytes (16 bits not signed)
60549	EC85	Averaged alarm 2 threshold	Type 3 Word	2 bytes (16 bits not signed)
99909	ECSC	Averaged alarm 2 threshold	Type 10 Word	2 bytes (16 bits not signed)
				Г
80676	ECA0	Averaged alarm 4 threshold	Type 10 Word	2 bytes (16 bits not signed)
				1 2 2 2 3 3 4 4 5 4 5 4 5 4 5 4 5 4 5 4 5 6 6 6 6 6
	JBUS			811 811 811 811 811 811 811 811 811 811
60677	ECA1	Faut Alarm Threshold		
60577	ECA1	Alarm threshold	Type 1 Word	2 bytes (16 bits not signed)
80678	ECA2	Aarm threshold	Type 2 Word	2 bytes (16 bits not signed)
60679	ECA3	Alarm threshold	Type 3 Word	2 bytes (16 bits not signed)
98909	ECAA	Aarm threshold	Type 10 World	2 bytes (16 bits not signed)
				2 2 7 9 9
	JBUS			18 18 18
60687	ECAB	Overscale Alarm threshold		
60587	ECAB	alam value	Type 1 Word	Г
88909	ECAC	alarm value	Type 2 Word	2 bytes (
68909	ECAD	alarm value	Type 3 Word	2 bytes (16 bits not signed)
96909	ECB4	alarm value	Type 10 Word	2 bytes (16 bits not signed)

	JBUS	The second secon		27 1189 27 1189 27 1189 21 1189 21 1189 21 1189 21 1181 21 1181 21 1181
76908	ECBS	Sveraged alarm 1 Delay	Type 1 Word	2 Mas (16 bits not stoned)
86909	ECB6	averaged alarm 1 Delay		2 bytes (16 bits not stared)
66909	ECB7	averaged alarm 1 Delay		2 bytes (16 bits not signed)
90909	ECBE			2 bytes (16 bits not signed)
/0000	ECBT	averaged alarm 2 Detay	Word Word	Z Dytes (16 bits not signed)
60909	ECCI	averaged alarm 2 Delay		2 bytes (16 bits not signed)
0.000	1000	managed plant 2 Delect		Distriction (4.0 bulbs and element)
01000	ECCO	avelaged and III z Detay	DOM:	Z DYRES (TO DIS TAL SIGNAL)
60636	ECDC	averaged alarm 4 Delay	Type 10 Word	2 bytes (16 bits not signed)
	9			21 11 12 12 13 14 15 15 15 15 15 15 15 15 15 15 15 15 15
26308	JBUS	Heriotogic Volino		
60637	ECDD	Hydrode	Tune 1 Word	2) hylas (18 h)ta not signad)
80638	CODE	Hydroxic		2 hydras (16 hite not storaid)
60909	ECDF	Hysteresis	Type 3 Word	2 bytes (16 bits not signed)
60646	ECE8	Hysteresis	Type 10 Word	2 bytes (16 bits not signed)
				2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
	JBUS			84 1 8 8 1 1 8 1 1
60647	ECE7	RESERVE COMOPS		
60647	ECEZ		Type 1 Word	2 bytes (16 bits not signed) 2 bytes (16 bits not signed)
60649	ECE9			2 bytes (16 bits not signed)
99909	ECF0		Type 10 Word	2 bytes (16 bits not signed)
	į			211 211 211 211 211 21 31 31 31 31 31 31 31 31 31 31 31 31 31
1	JBUS	The second second second		
/0000	ECF	Elizbe u disable Alalilis		
2909	ECF1	Type 1(1 byte)	Type 2 (1 byle) 2 byles	MA SWELOLI MA SWE
				4 no
8909	ECF2	Type 3 (1 byte)	Type 4 (1 byle) 2 bytes	Teke 314er Ah 3reer Ah 1res C An 1re
		:		
				S aver On S aver On S has on S has on S has on S has on S has on S has on S has on S has on S has on S has on S has on
60661	ECF5		Type 10 (1 byte) 2 bytes	51A 51A 51A 51A 51A 51A 51A 51A 51A
		# bit= 1 enable alarm		

	Sille				21 118 21 118 21 118 01 118 8 118	3118 3118 418 510 510 7118 7118
80662	ECF6	Checking of the type of compeded detector				
60662	ECF6	Type 1 (1 byte)	Type 2 (1 byte)	2 bytes	Code detector type 1	Code detector type 2
89909	ECF7	Type 3 (1 byte)	Type 4 (1 byte)	2 bytes	Code detector type 3	Code detector type 4
80668	ECEA	Type 9 (1 byte)	Type 10 (1 byte)	2 hytes	Code delector type 9	Code detector type 10
					11 11 10	2 2 9
	JBUS				181 181 181 181 181 181 181 181 181 181	1181 1181 1181 1181 1181 1181 1181 118
19909	ECFB	Gas name				
29909	ECFB	Gas name for type 1 (5 bytes)			Name 1 Byte 1	Nom 1 Byte 2
69909	ECFD	Gas name for type 1 and 2 (5 bytes)			Norm 1 Byte 5	name 2 Byte 1
0.000	ECFE	Gas name for type 2 (5 bytes)			name 2 Byte 2	name 2 Byte 3
60671	ECFF	Gas name for type 2 (5 bytes)			name 2 Byte 4	name 2 Byte 5
60691	ED13	Gas name for type 10 (5 bytes)			name 10 Byte 4	Name 10 Byte 5
	!				21.1 21.1 21.1 01.1 81.3	31 31 51 51 51 51
	JBUS					
60692	ED14	Gas shortened name				
60692	ED14	Gas name for type 1 (16 bytes)			name 1 Byte 1	Name 1 Byte 2
66909	ED1B	Gas name for type 2 (16 bytes)			Name 2 Byte 1	Name 2 Byte 2
60771	ED63	Gas name for type 10 (16 bytes)			Name 10 Byte 15	Name 10 Byte 16
	<u>z</u>				21 110 S1 110 S1 110 O1 110 8 110	2 Ht 2 Ht 2 Ht 2 Ht 2 Ht 2 Ht 2 Ht 2 Ht
80772	EDBA	Inisplay format				3
60772	ED84		Type 271 byte)	2 bytes	Display format code type 1	Display format code type 2
60773	ED85	Type 3 (1 byte)	Type 4 (1 byte)	2 bytes	Display format code type 3	Display format code type 4
80778	ED88	Tyre 9/1 byte)	Type 10 (1 byte)	2 hytes	Distribution at code fore 9	Display format code fune 10
		C - 00 Of Johnson and Poster State of	= 2 diale offerthe point in (m)	4	and a section of the	

0.18				Г	[]	0	18					
1118		feaanunsm FIA=F	Jəsəi unamı FIA=F		βəsən unsαn tiA=t		18		levisnonilNA=0	teve1ori NA=0		nevenonillA≕(
2118			1saen unem SIA=f		1saen unsm SIA=f	⊢	:18		eve nor ave	neve nori SIA=0		ieve roni ⊠A=0
E#8		feaeπunsm.€M=f	1eaen unam EM=f		teset unsm.€IA=f	⊢	:18		ievs πori 81A=0	nevs nori 8lA=0		evs non 8A=0
		teaen unam MA=t	teser unem MA=t		teser unsm.MA=t	⊢			neveroni MA=0	nevs tori blA=0		neveroni MA=(
1718		J=overtange	1=overrange		f=overrange	⊢	18		iewsnoniNA=0	teverani NA=0		nevsnonillA≕(
9118						⊢	18		eve roni ⊈A=0	neve nori SIA=0		teve toni ⊈A=0
9 118						⊢	18		everonitA⇔0	nevs nori EIA=0		1e∧s noraver
7 118						1	18		nevs noni MA=0	nevs nori ≱lA=0		neveroni ≱lA=(
8 11/9		teearunam MA=t	teser unem tiA=t		teser unem tiA=t	8	318		ievenon illA≕0	nevenori NA=0		ieveroniNA≕(
6 #8		jesetunsm SIA=f	jese⊓unem SIA=t		jesenunem SIA=t	6	318		everoni∑lA=0	neve tori SIA=0		neveroni ⊈A=0
or ha		leaenunsm ElA=f	lesenunem ElA=f		besenunem ElA=f	01	18		ievs noni 81A=0	neve toni 8lA=0		teve non i 8lA=0
rr 118			jeserunam ⊅M=t		iesenunem ⊅M=t	LL	18			nevs nori MA=0		neveroniblA=(
Sr 119		ј=сиензиде	1=cve nange		e6ueu evo=↓	ZI	18			nevs nori MA=0		heveronitA=(
Et 18		,	,			13	18			neveroni SIA=0		iewsnoni⊠A=0
141 118						tri	18			neva nori 8lA=0 neva nori 8lA=0		19ve nori 8A=0 74 increase
ar 118						91	. 18			Teve ori 4tA=0		1e∧BonitAA=0
_			_	H		L			zowo ogi NA≡0			
		Dytes	2 Dytes		2 bytes				bytes	bytes		2 bytes
		2	2		2				2	2		2
												_
		byte)	byte)		byte)				byte)	byte)		Market (september 1987)
		Type 2 (1 byte)	Type 4 (1 byte)		Type 10 (1 byte)				Type 2 (1 byte)	Type 4 (1 byte)		Done 10 (1 byte)
		Type	Type		J.pe) yes	Jype		902
								aam				
	ILLER							easing alarm				
	8 pag							ecrea				
	EUI J	byte)	pyte)		byte)			000) Afe	byte)		e page
	0 De(Type 1 (1 byte)	Type 3 (1 byte)		Type 9 (1 byte)			Dusseuc	Type 1 (1 byte)	Type 3 (1 byte)		Tope 971 bytel
	Enal	Туре	Type	:	Туре			lncre	Type	Туре	:	706
Snac	69CE	69C3	ED6A		EDGD		JBUS	39C3	39C3	ED6F		2,013
8	Ξ	Н		-	Ш			Ξ	Ш	Ш		
	_		201		_			2	Ν.	m		
	11109	11109	8778		60781			28/09	28709	60783		98209
											_	

		JBUS			21 118 21 118 21 118 11 118 9 118	311 0 31 0 31 0 31 0 31 0 31 0 31 0 31
Type 3(1 byte) Type 2(1 byte) Type 2(1 byte) Type 2(1 byte) Type 3(1 byte) Type 4(1 byte) Type 1(1 byte) Type 1 Type 1(1 byte) Type 1 Type	60787	ED73	PS			
Type 3 (1 byte) Type 4 (1 byte) Type 1 (1 byte) Type 1 (1 byte) Type 1 (1 byte) Type 1 (1 byte) Type 2 Type 3 Type 4 Type 5 Type 4 Type 5 Type 6 Type 7 T	60787	ED73			Sk	
ED77 Type 9(1 byte) Type 10 (1 byte) Type 10 (1 byte) Type 10 (1 byte) Type 10 (1 byte) Type 2 Type 2 Type 2 Type 3 Type 3 Type 3 Type 3 Type 3 Type 4 Type 4 Type 4 Type 4 Type 4 Type 5 Type 4 Type 5 Type 6 Type 6 Type 6 Type 6 Type 6 Type 6 Type 7	60788	ED74			St	
FD7						
DBUS Marm Delay Type 1 Word ED/8 Marm Delay Type 2 Word ED/8 Marm 1 Delay Type 2 Word ED/8 Marm 1 Delay Type 3 Word ED/8 Telas not signed) Type 1 Word ED/8 Telas not signed Type 1 Type 1 Word ED/8 Telas not signed Type 1 Type 1 Word ED/8 Telas not signed Type 1 60791	ED77			S		
ED78 Alarm Delay Lipe 1 World 2 bytes (16 bits not signed) ED78 Alarm Delay Lipe 2 World 2 bytes (16 bits not signed) ED74 Alarm 1 Delay Lipe 2 World 2 bytes (16 bits not signed) ED84 Alarm 2 Delay Lipe 1 World 2 bytes (16 bits not signed) ED84 Alarm 2 Delay Lipe 2 World 2 bytes (16 bits not signed) ED84 Alarm 2 Delay Lipe 2 World 2 bytes (16 bits not signed) ED84 Alarm 2 Delay Lipe 2 World 2 bytes (16 bits not signed) ED84 Alarm 2 Delay Lipe 2 World 2 bytes (16 bits not signed) ED84 Alarm 2 Delay Lipe 2 World 2 bytes (16 bits not signed) ED84 Alarm 2 Delay Lipe 2 World 2 bytes (16 bits not signed) ED84 Alarm 2 Delay Lipe 2 World 2 bytes (16 bits not signed) ED85 Alarm 4 Delay Lipe 10 World 2 bytes (16 bits not signed) ED85 ED86						
BLDS					10 13 13	1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
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JBUS EDA0 Detector type Range EDA0 EDA0 </th <th>60831</th> <th>ED9F</th> <th></th> <th></th> <th></th> <th></th>	60831	ED9F				
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EDA2 Range Type 1 Word EDA2 Range Type 2 Word 5 EDA2 Range Type 3 Word 5 EDA9 Range Type 10 Word 5	60832	EDAO	Detector type Range			
EDA1 Range Type 2 Word EDA2 Range Type 3 Word EDA9 Range Type 10 Word	60832	EDA0	Range		П	
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EDA9 Rarge Type 10 Word	60834	EDA2		3	2	
EDA9 Range Word Word					П	
	60841	EDA9				



DECLARATION UE DE CONFORMITE EU Declaration of Conformity



La société Oldham S.A.S., ZI Est 62000 Arras France, atteste que la Oldham S.A.S. company, ZI Est 62000 Arras France, declares that the

Système de mesure CPS – Monitoring system CPS

Incluant la centrale de mesure, les détecteurs de gaz, les modules E/S et relais Including the controller, the gas detectors, the relays and I/O modules

> est conforme aux exigences de: complies with the requirements of the following Directives:

I) Directive Européenne CEM 2014/30/UE du 26/02/14: Compatibilité Electromagnétique

The European Directive EMC 2014/30/UE dated from 26/02/14: Electromagnetic Compatibility

Normes harmonisées appliquées: EN 50270:06 for type 1&2 Harmonised applied Standards

CEM-Appareils de détection de gaz EMC-Apparatus for the detection of gases

II) Directive Européenne DBT 2014/35/UE du 26/02/14: Basse Tension

The European Directive LVD 2014/35/UE dated from 26/02/14: Low Voltage

Normes harmonisées appliquées: EN 61010-1:10

Harmonised applied Standard

Règles de sécurité pour appareils électriques de mesurage Safety requirements for electrical equipment for measurement

III) Norme de performance métrologique

Metrology Performance Standard

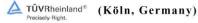
Normes appliquée Applied Standard

Organisme certificateur Certification Body

Rapport d'essai Test Report

VDI 2053:04, Annex2,

Mesure du CO (CO measurement)



S274 2007 T1

Arras, le 20/04/2016 (April 20th, 2016)

Michel Spellemaeker



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Global Director of Product Management

UE CPS revA



Thank you for reading this data sheet.

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Please note - Product designs and specifications are subject to change without notice. The user is responsible for determining the suitability of this product.